

# Production-ready Diagnostics with Apex.OS

Apex.AI

Industry standard diagnostics for ROS 2

Apex.OS

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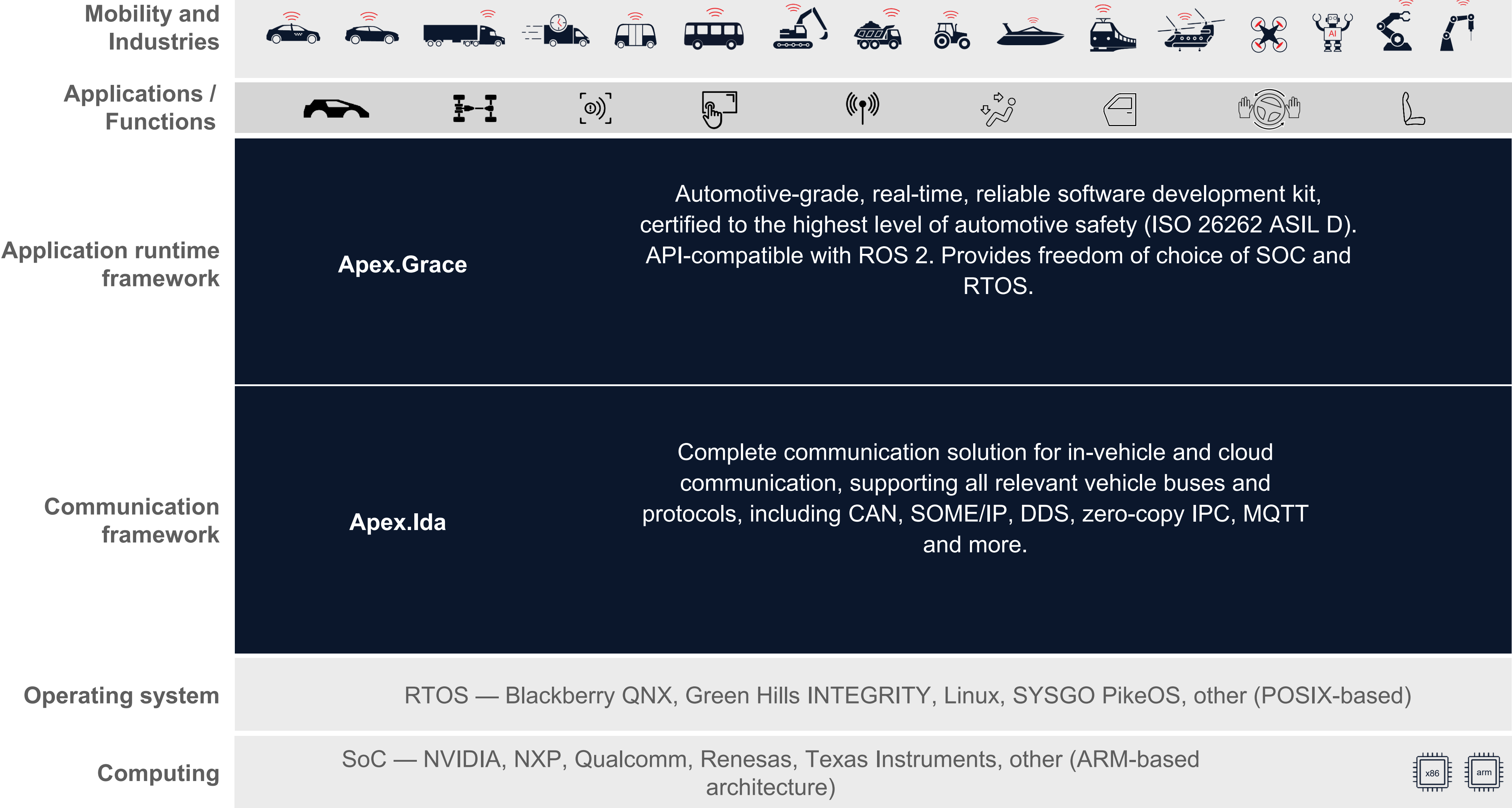


# Agenda

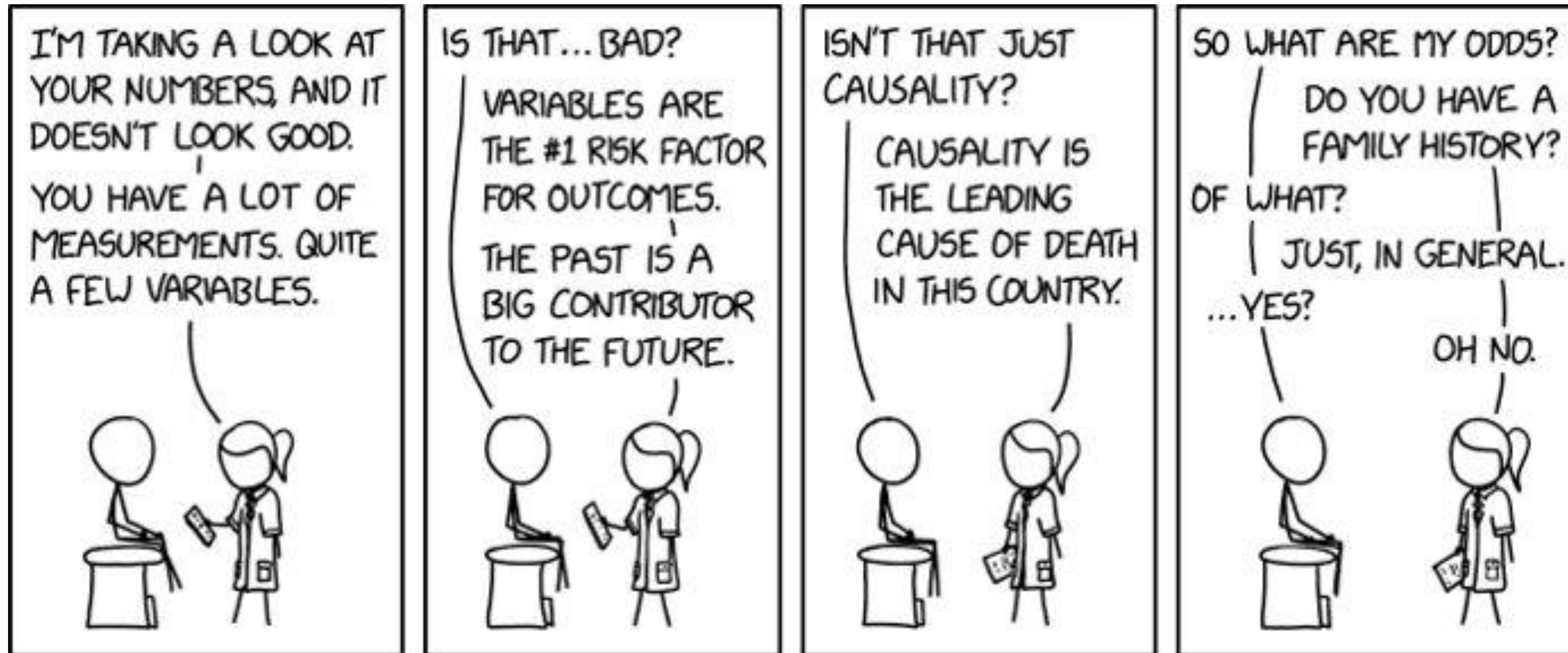
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# Apex.OS introduction



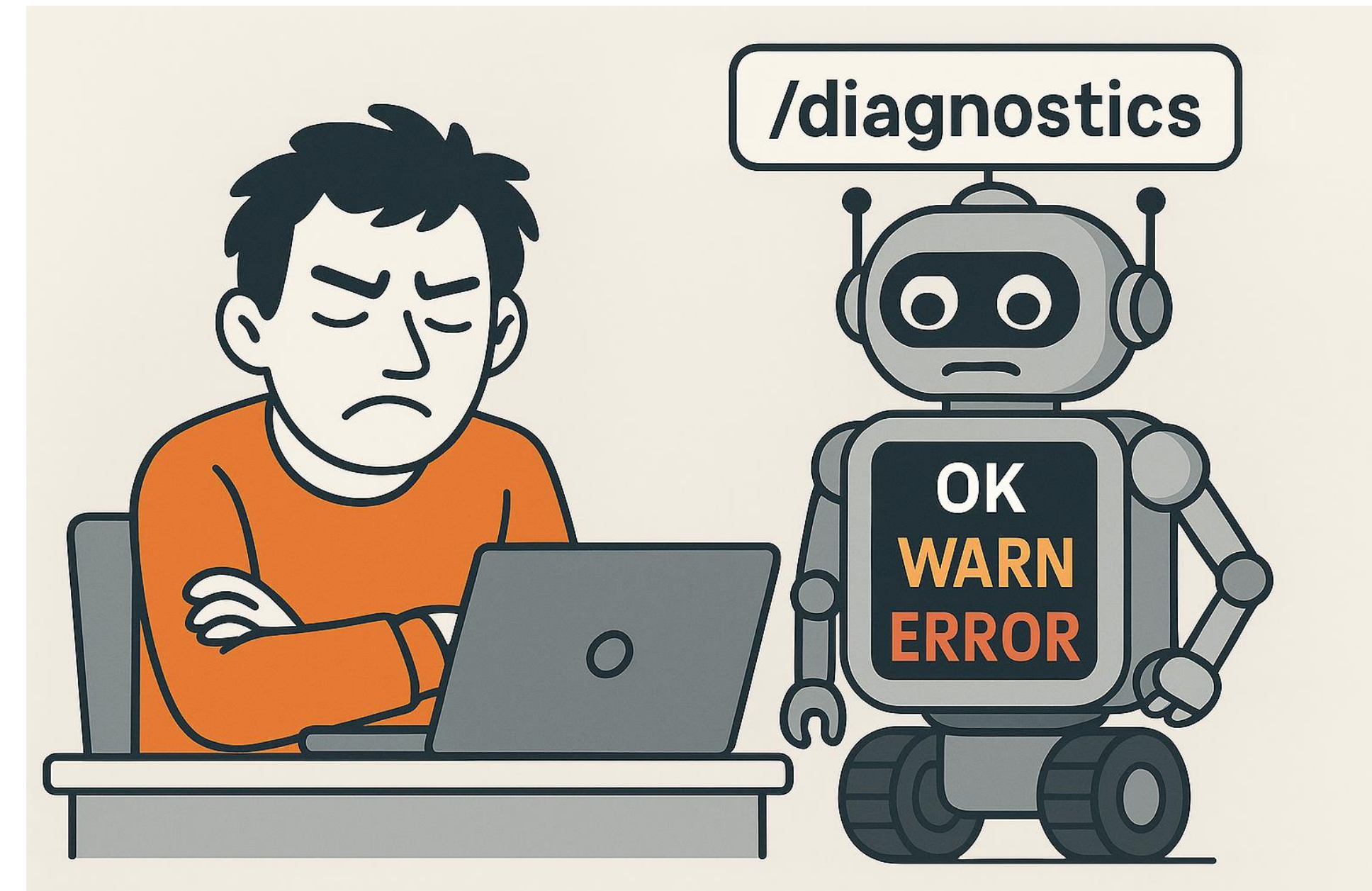
Apex.OS





# ROS 2 Diagnostics: Minimal API, Maximum Ambiguity

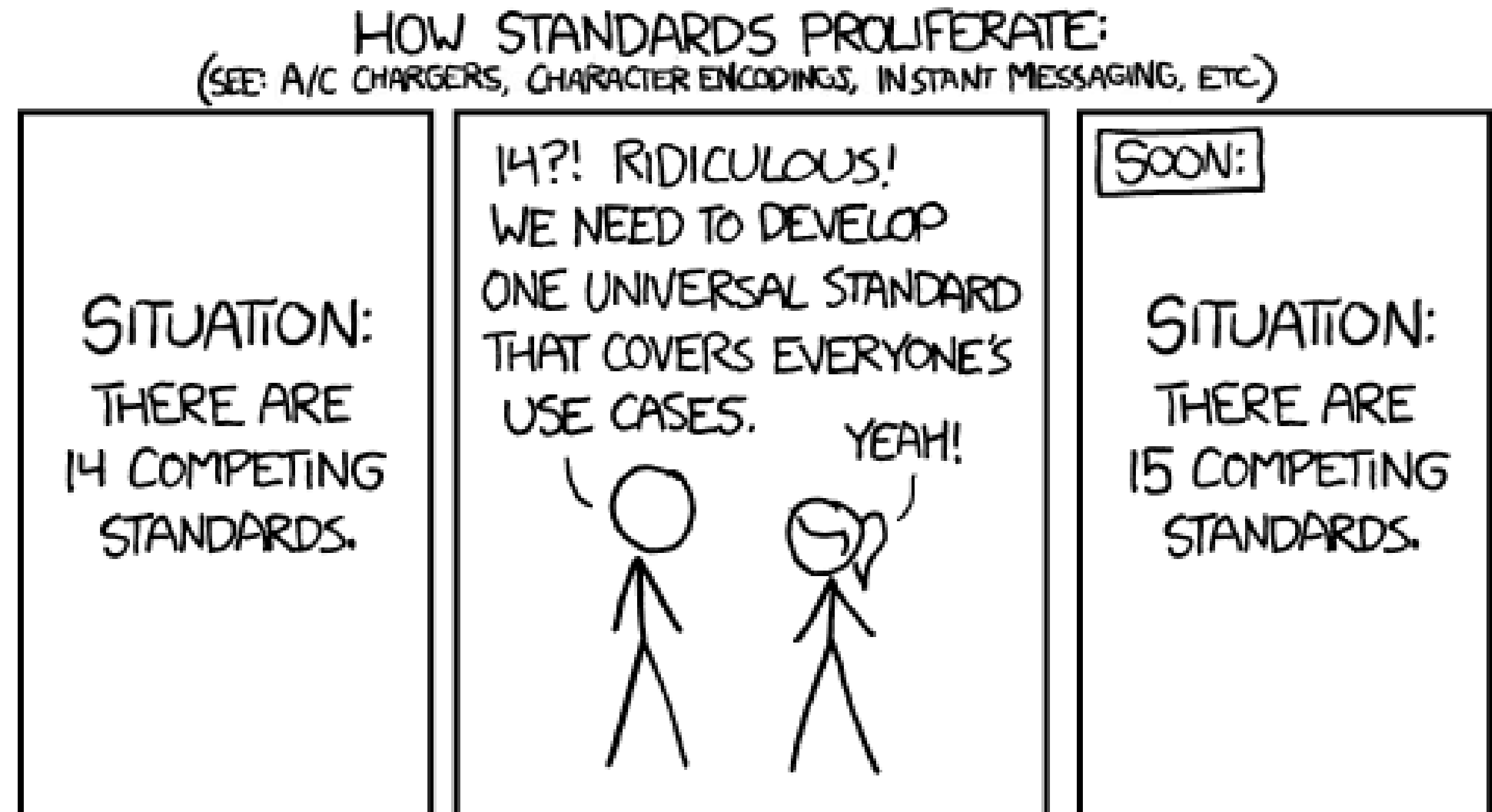
- ROS 2 diagnostics can tell your robot feels **kind of** unwell. No tests, no procedures, no history => **No diagnosis !**
- Just turn it OFF and ON again. No errors!! Great !?
- Robots are getting smarter (Hello Physical AI!) — their **diagnostics shouldn't stay dumb.**
- **Apex.OS** brings the medical-grade checkup that ROS 2 has been missing.



**There has to be a better way of doing Diagnostics !**

# New Diagnostics Standard? No!

- **This is a solved problem** with certified diagnostic systems available in every workshop. (Remember your car's last TÜV inspection?)
- In automotive, diagnostics is full triage: **codes, causes, context, and persistency**
- Robotics needs the same **attention to detail** !
- The physical infrastructure already exists to diagnose and service your robots, **if we use the same standard!**

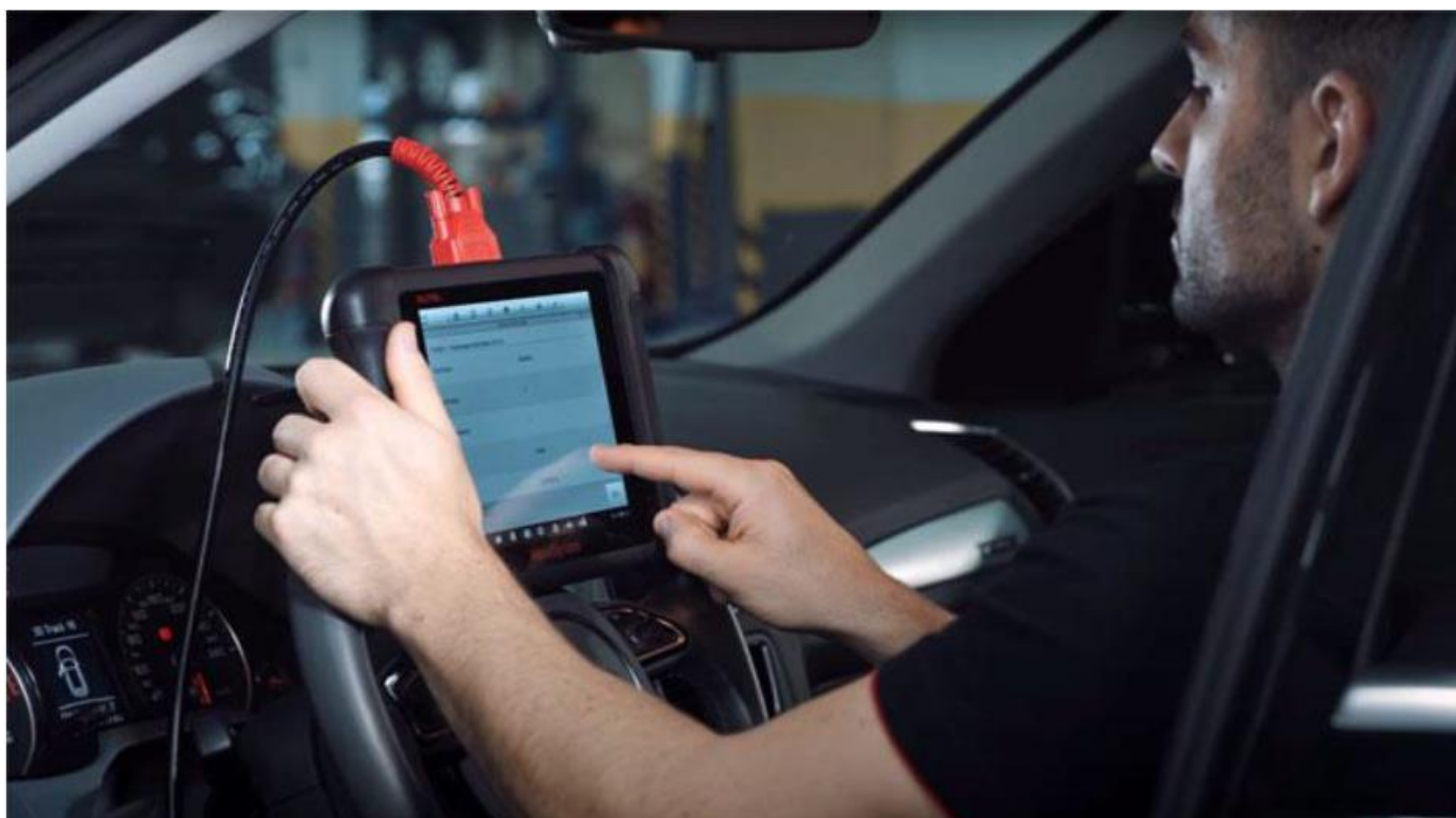


**Apex.OS integrates standardized vehicle diagnostics into ROS 2**



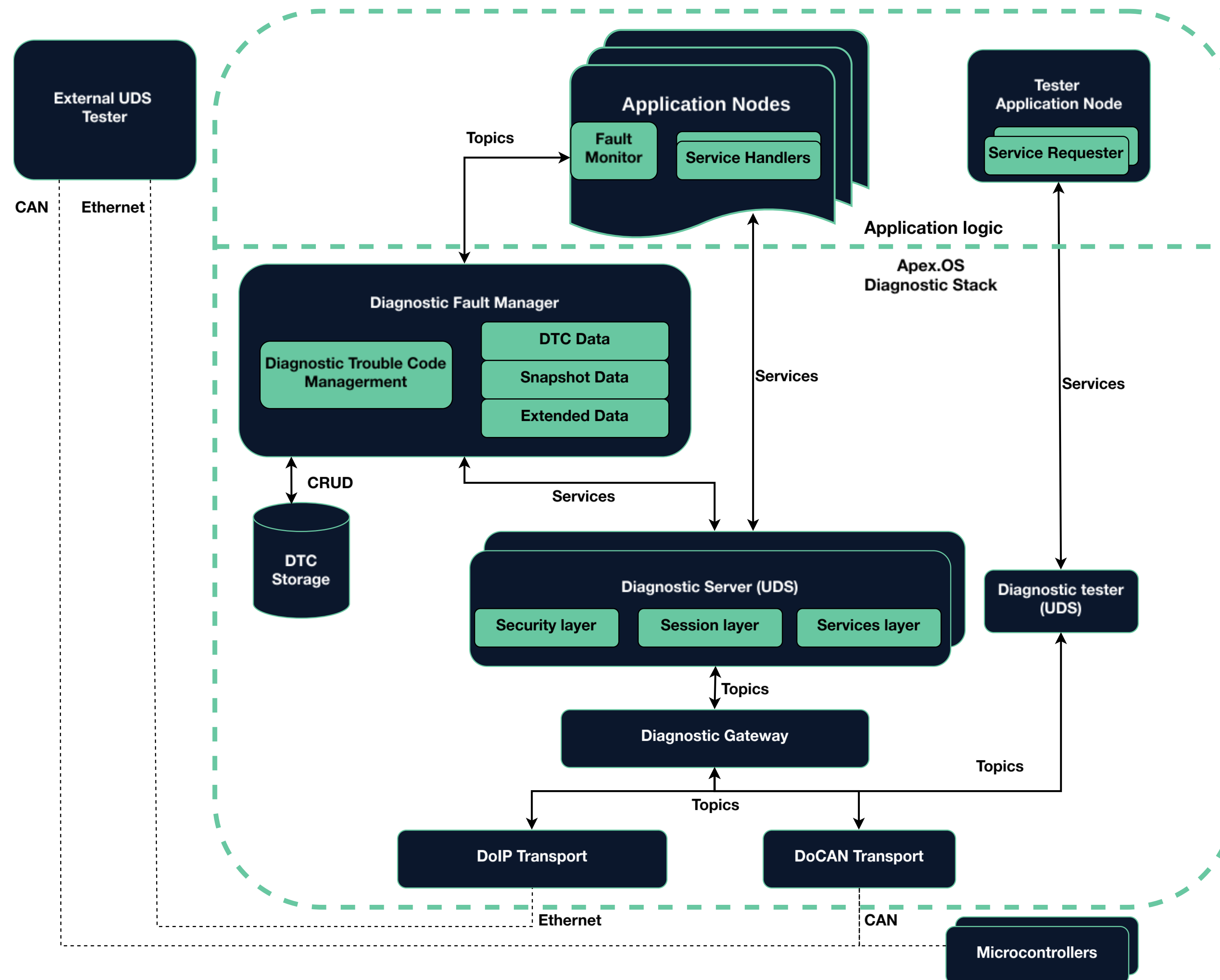
# 01

## Apex.OS Diagnostics Architecture





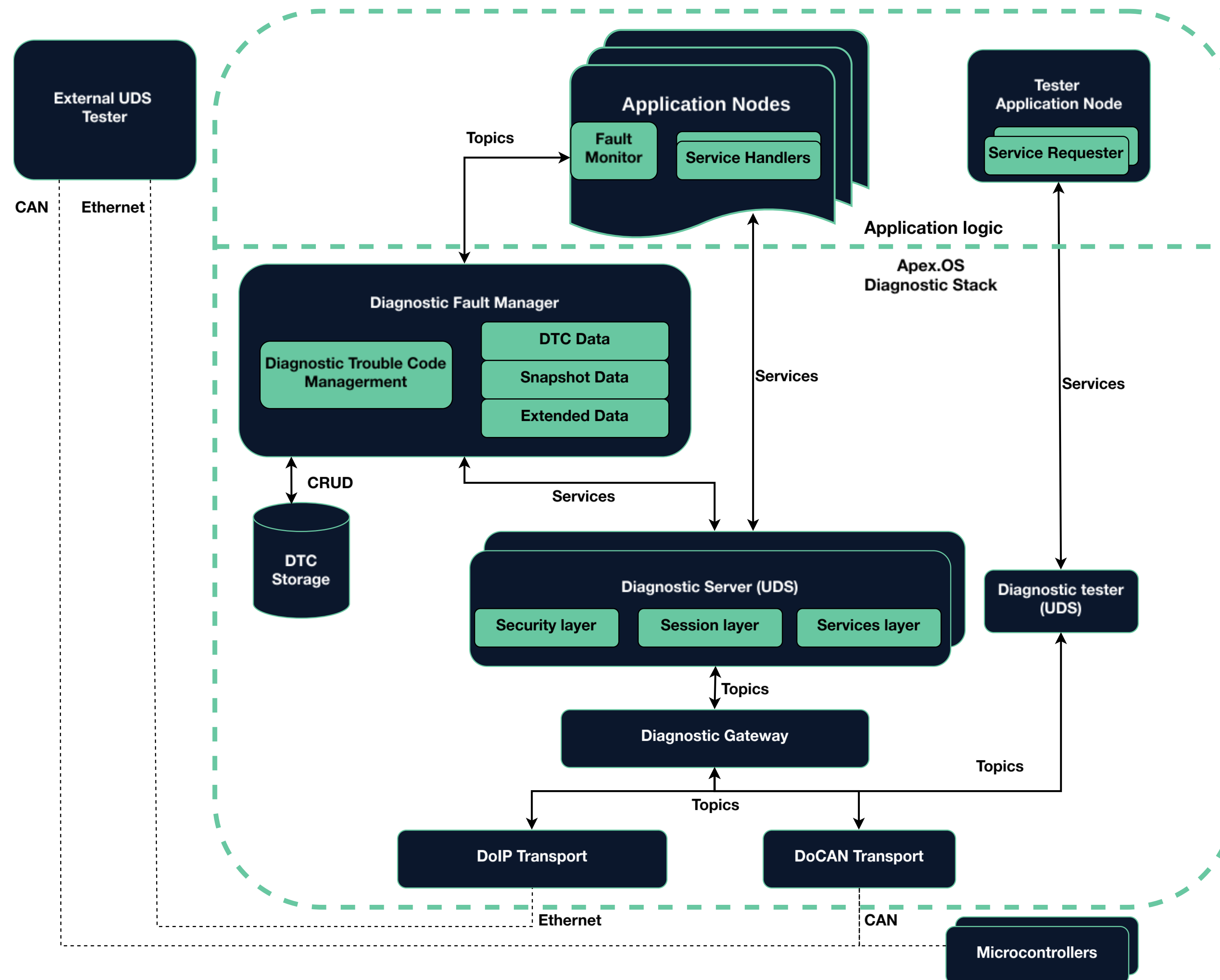
# Apex.OS Diagnostics Overview



- Production ready diagnostic stack aligned with **automotive diagnostic standards**
  - **ISO 14229 (Unified Diagnostic Services)**,
  - **ISO 13400 (Diagnostics over IP)**,
  - **ISO 15765 (Diagnostics over CAN)**
- Modular architecture built on top of ROS 2 communication primitives such as Topics and Services.
- A diagnostics stack that allows not just monitoring and fault management, but also calibrating parameters during production and post-market servicing.



# Apex.OS Diagnostics Architecture



## Key Modules:

- **DoIP/ DoCAN transport** Nodes convert frames to ROS 2 msg and publish it on topics.
- **Gateway** routes the requests to the right server.
- **Diagnostic Server** implements the **UDS** protocol and ensures secure access control while fetching the application node data.
- **Diagnostic fault manager** detects and persists the faults and context
- **Diagnostic tester** provides a ROS 2 native way of communicating with the Diagnostic stack

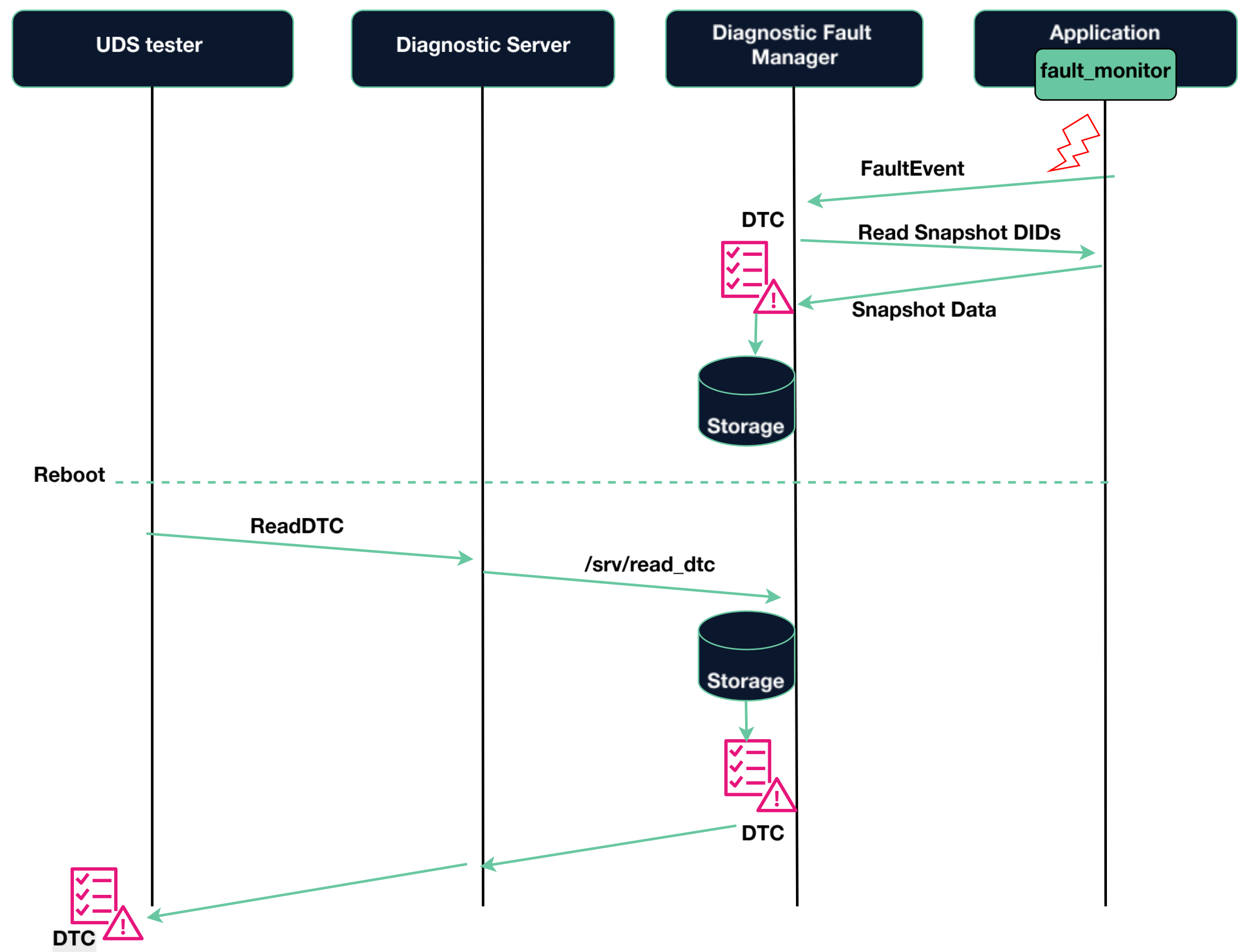


# 02

## Use-cases & Demos

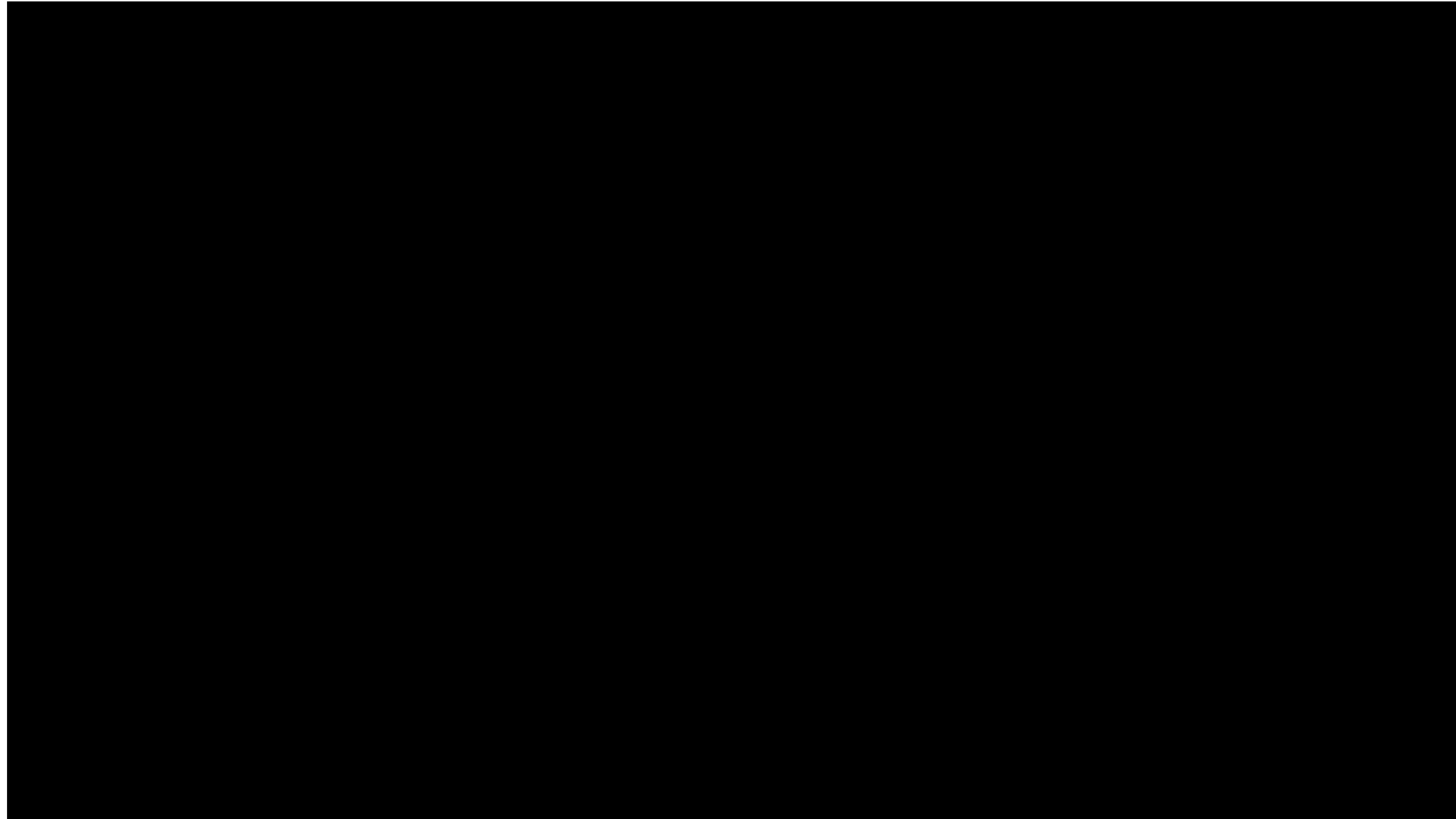


# Fault management



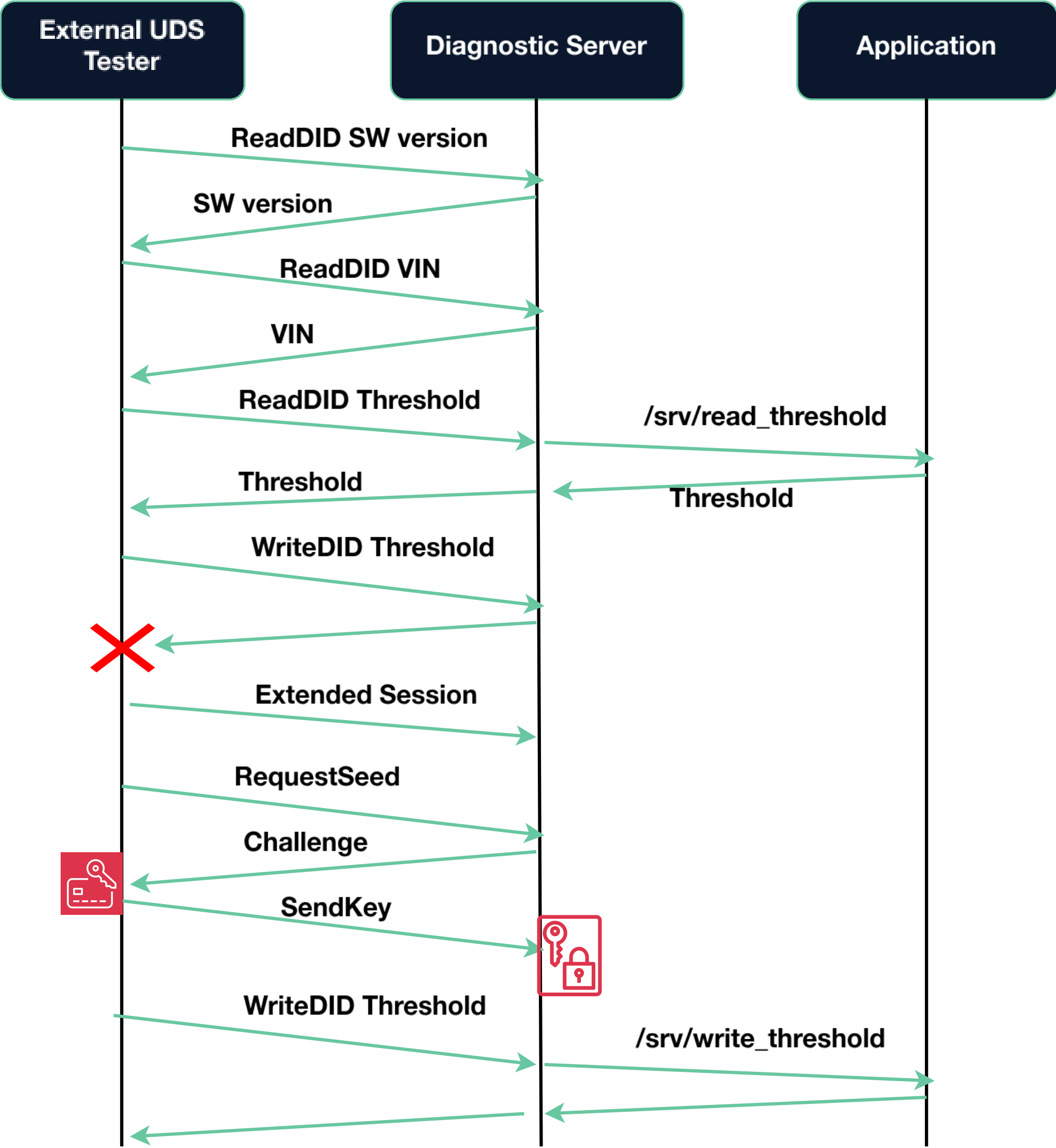


# Fault management Demo



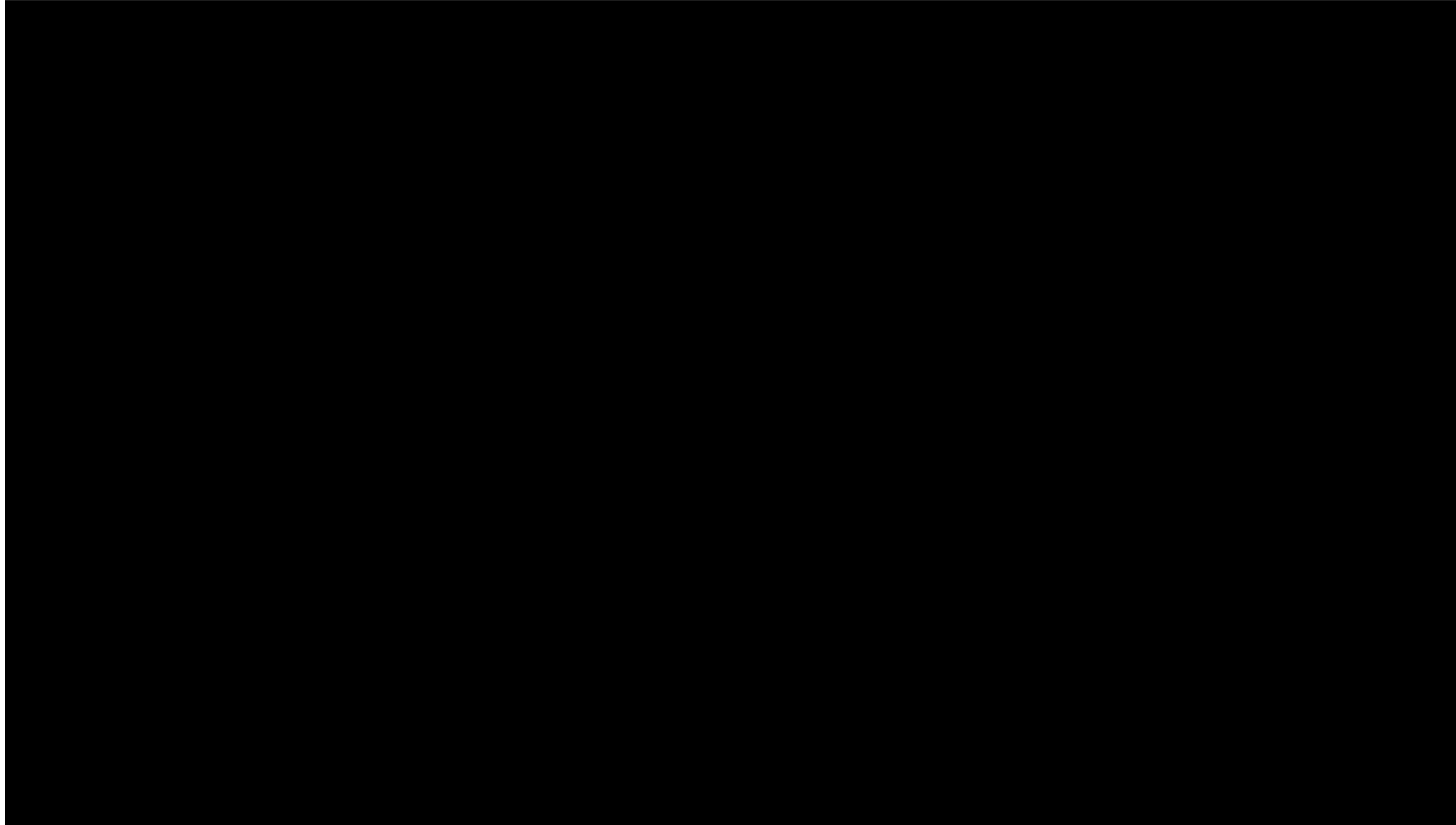


# Secure Access and Diagnostics



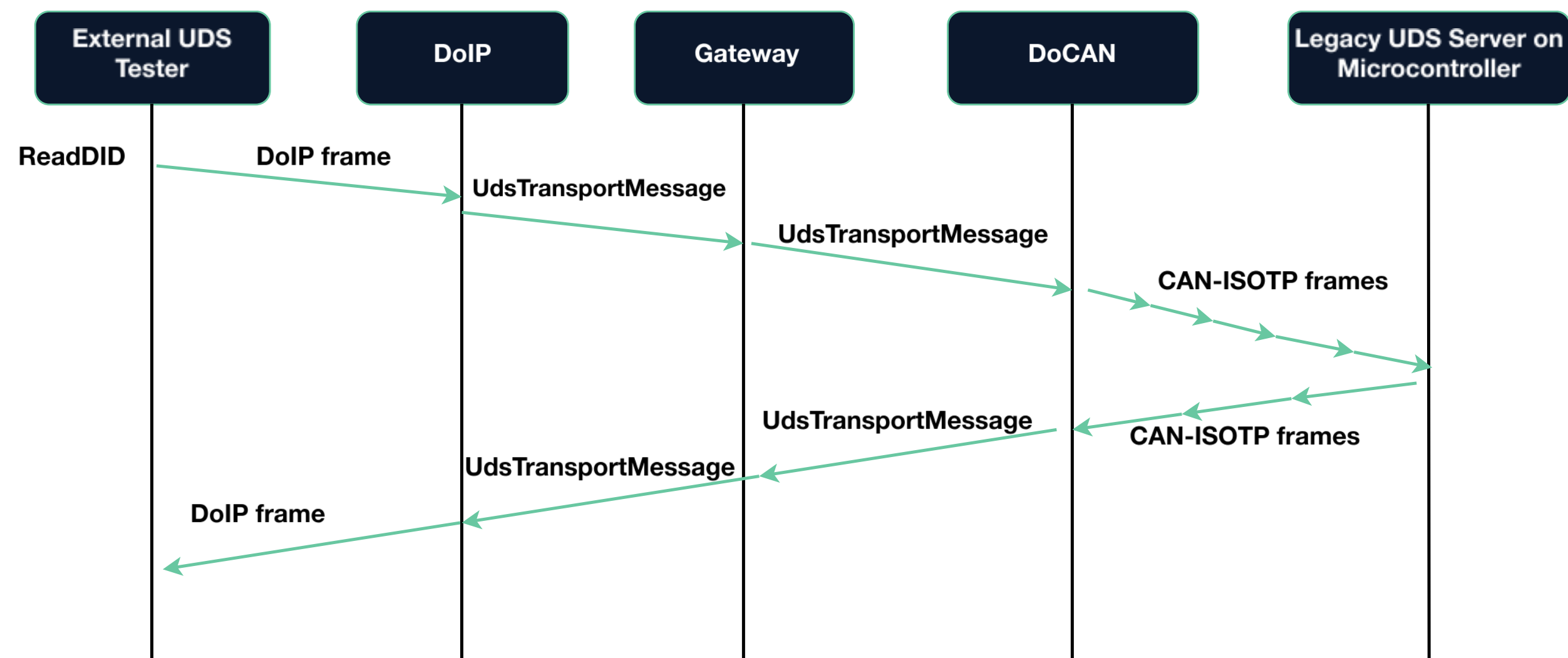


# Secure access and Diagnostics Demo



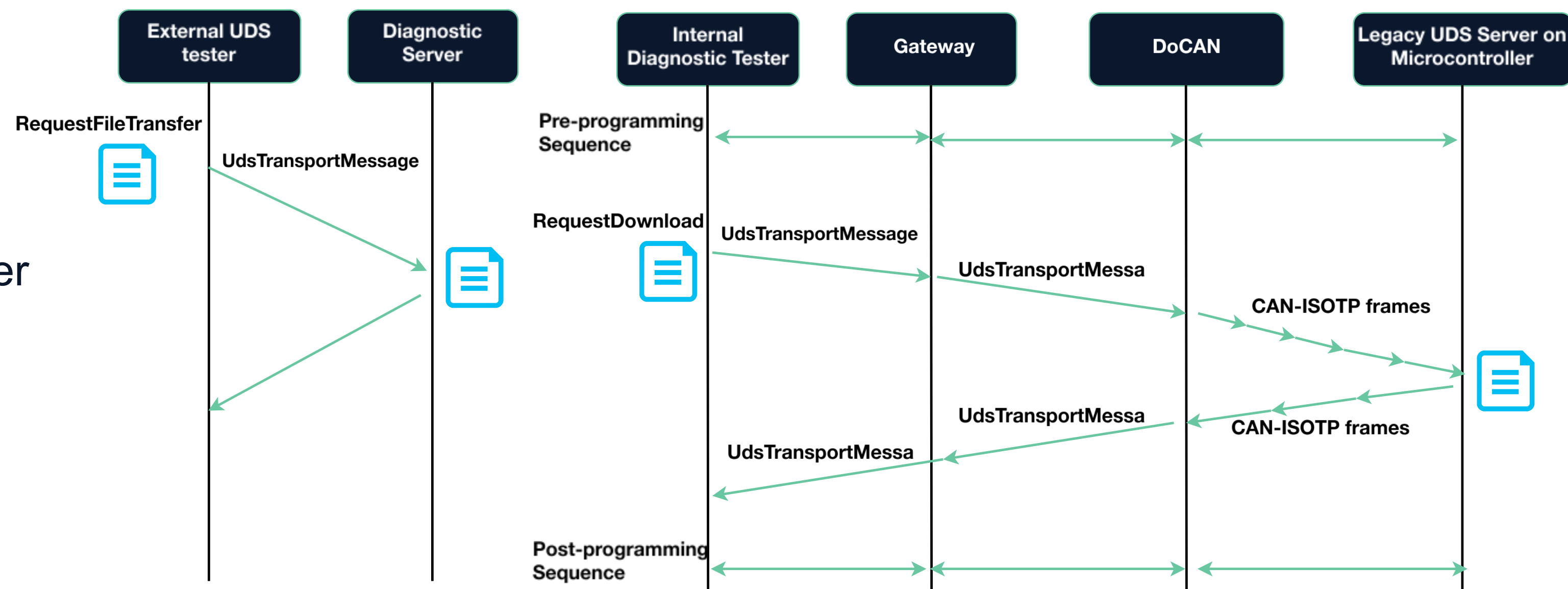


# Mixed network topology and software update



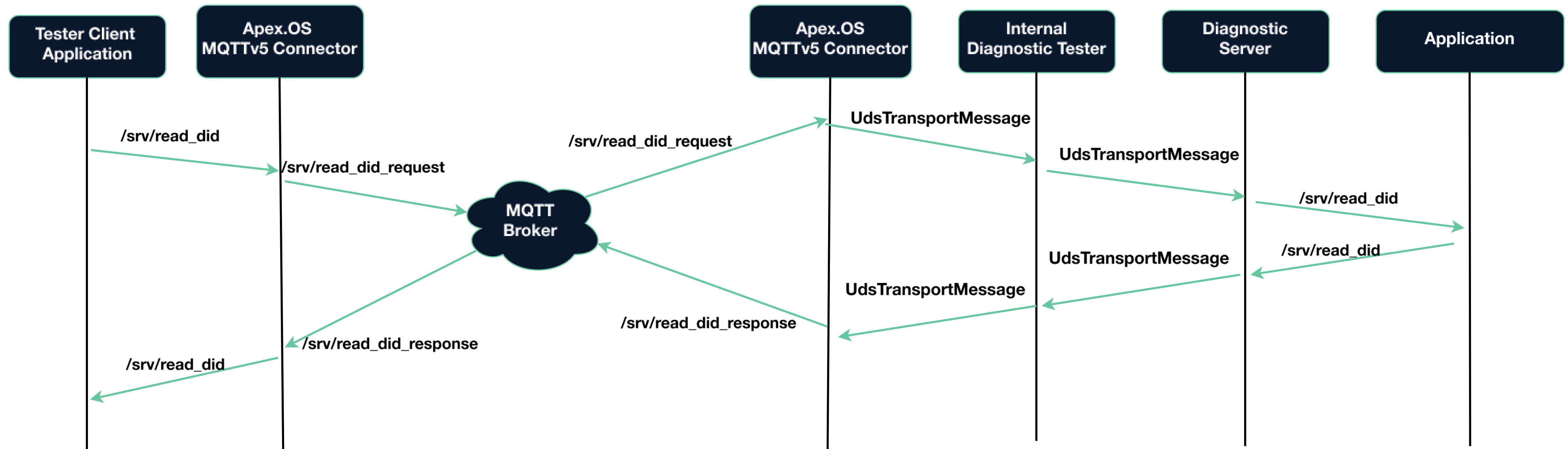
- An External UDS tester connected over ethernet can be used for diagnosing a legacy microcontroller that is connected to target board via CAN

- UDS Services such as RequestFileTransfer and RequestDownload can be used for doing a software update.





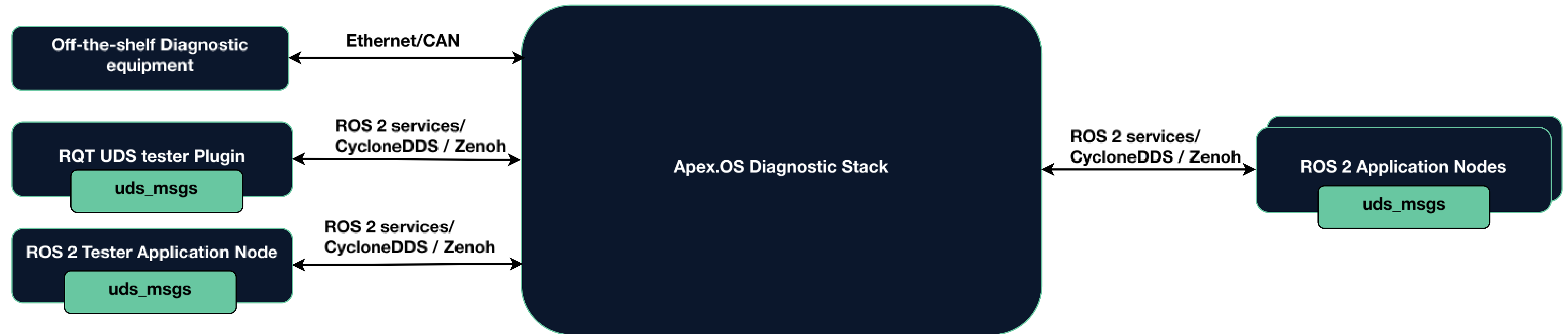
# Remote diagnostics



- Connecting the Diagnostic stack to the Apex.OS MQTT connector, remote diagnostic capabilities can also be realized.



# ROS 2 integration



- Abstracts away UDS protocol specific logic and ROS 2 developers can focus on the business logic using the topics and service interface.
- Enables ROS 2 systems to interface with off-the-shelf diagnostic equipment to enable service and maintenance



# 03

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## Summary and next steps



# Summary and next steps

- **Apex.OS extends ROS 2** with an **ISO-standard compliant diagnostics framework**, bridging robotics middleware with automotive-grade fault management.
- Apex.AI plans to open-source parts of our Diagnostics stack.
- We plan to continue to update our diagnostics stack with newer standards such as ASAM SOVD.



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