Open-RMF and the Challenge of Resource Contention in Large-Scale Robot Fleets

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Currently available Open-RMF features

- **V** Traffic Management
- Task allocation
- Task scheduling
- Charging Schedules
- ?? Resource allocation







Resource Contention and Robots

- Lifts
- Parking spots
- Chargers
- Tool heads
- Carts





Resource deconfliction?

I need to charge. I can charge at charging station 1 or station 2

I need to charge. I can charge at charging station 2























Robot 2 has task:

GoToPlace { one_of: [p1, p2] }

pen-RMF













Caveats

- There must be at least the same number of parking spots as robots available.
- The node must be explicitly enabled.
- The queue is FiFo



Video Demonstration



In this example tinyRobot2 is asked to go to the pantry first.

tinyRobot1 is told it can go to Either the lounge or the pantry.

The reservation node correctly allocates each robot to its final destination.



Video Demonstration





To Enable

In your fleet configuration:

```
rmf_fleet:
name: "tinyRobot"
limits:
   linear: [0.5, 0.75] # velocity, acceleration
   angular: [0.6, 2.0] # velocity, acceleration
...
use_parking_reservations: True
```



To Enable

Also launch the reservation queue

<node pkg="rmf_reservation_node" exec="queue manager"></node>

Example Config Available in this PR:

https://github.com/open-rmf/rmf_demos/pull/212/files





Sneak Peek Of Next Gen Capabilities



Motivation

- We can check resource constraints at runtime but what if there are tasks that have to be completed by some deadline?
- Example could be that there are robots waiting for their next charge blocked by a counterpart that is reusing the same space for some other task.



Introducing rmf_reservations

- Rust-based resource constrained schedule library
- Can be used at the task scheduling level
- Currently proof of concept is ready but exact APIs are unstable and will change
- Submit a set of resource constraints and requests. Get back feasibility immediately. Find optimal solution slowly.
- Paper presented at IROS 2024 outlining the algorithms.
- Unlike Google-OR tools our formulation does not need integer costs.









Alternatives can have costs. For instance we can use distance to charger as a cost function.











Arxiv Link To Paper





Feasibility via SAT For problems with obvious solutions. For a request size of n there are n alternatives. I.E for 40 requests there are 40 alternatives each



Questions?



PR Documenting How to use in current generation



RMF Reservations Source code



Arxiv Link To Paper

