

The background of the slide is a dark, blue-tinted photograph of a car, possibly a Tesla, driving on a bridge. The bridge's steel truss structure is visible in the background. Overlaid on this image is the Apex.AI logo, where 'Apex' is in white and '.AI' is in a light green color.

Apex.AI

launch_testing in ROS 2

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Agenda

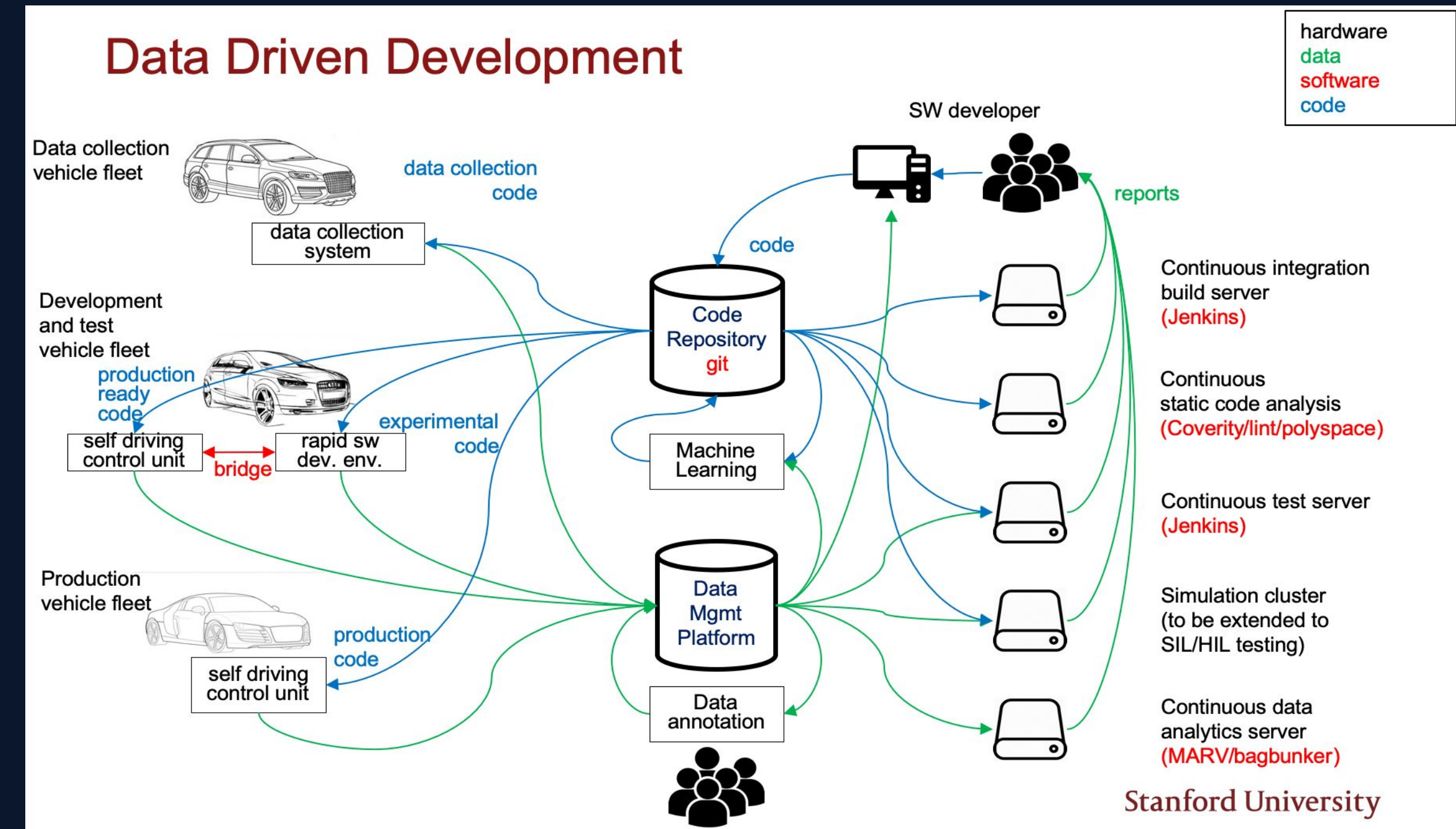
- Integration testing
- *rostopic*
- ROS 2 launch
- *rostopic* improvements
- *launch_test*
- *launch_test* example
- *launch_test* demo



Motivation for Integration Testing

Integration testing is where software modules are integrated logically and tested as a group

- Clear API boundary between processes being tested
- Integration tests checks the real program flow
- Integration tests check the real user interactions
- Unit tests often uses bespoke configurations and can miss issues with real configurations
- Unit tests are often single-threaded, and don't expose complex race conditions
- Performance testing



ME 302B: Stanford University; Jan Becker

Lack of Integration tests!
2 Unit tests, 0 Integration tests

rostopic (from ROS 1)

- It is an integration test suite based on ***roslaunch***
- Has `<test>` tag in the xml file, which specifies the test nodes to run
- *rostopic's* *roscore* is restarted for each test
- By default *rostopic* uses random ports, so many *rostopic's* can run in parallel and in isolation
- Launches all of the processes from a launch (xml) file, then waits for the test process to finish
- The final exit code is based on the exit code of the test process

launch and launch_ros in ROS 2

- **launch** is a ROS-agnostic tool to launch processes
- **launch_ros** is a tool to launch ROS nodes
- ROS 2 launch is exposed as a Python API
- ROS 2 launch API is extendable and supports adding custom actions and events
- ROS masters are no longer required for nodes to communicate
- **launch** can use events for feedback and have actions that create other actions
- **launch** descriptions can be introspected

New Challenges:

- ROS 2 launch descriptions can be arbitrarily complex and they themselves need to be tested

Rough Edges In rostest

- Tests might run before the processes under test were ready
 - This results in a test failure, which might be hard to reproduce
- Processes under test might crash, and tests would not notice this crash
 - Results in a test failure, which would be difficult to reproduce
- Debug output like *stdout* or *stderr* from tests might be hard to find
 - This makes it difficult to analyse the *stdout* or *stderr* streams to align output with the test cases

Improvements on rostest Functionality

- What if there was a way for the test author to explicitly coordinate when the test runs with the processes under test?
 - ***launch_testing*** has a ***ReadyToTest()*** action that coordinates test start with the rest of the launch
- What if tests could access process information like the exit codes of launched processes?
 - ***launch_testing*** has a ***ProcInfoHandler*** object, which has exit code information for processes that were launched
- What if tests could access process information like *stdout* or *stderr* of launched processes?
 - ***launch_testing*** has an ***IOHandler*** object, which has *stdout/stderr* information for processes that were launched
- What if we could automatically generate test cases for the launched processes?
 - Ability to introspect the launch description makes it easy to programmatically generate test cases

launch_testing

- ***launch_testing*** is a framework for integration testing based on the ROS 2 launch system
- The exit codes, *stdout* and *stderr* of all processes launched are available to the tests
- The command-line used to launch the processes are available to the tests
- Tests can run concurrently with the launched processes, or can run after the launched processes are shut down
- Output looks like regular unit-test output; each test case gets a line
- Parametrize the launch description
- ***launch_testing_ros*** can automatically generate a unique *ROS_DOMAIN_ID* to isolate tests from one-another to be able to run the tests in parallel and in isolation

Timeline of a launch_test Command

T+

“Active” tests. May interact with running processes via ROS or other means, or just observe

“Post-Shutdown” tests. Can access recorded stderr, stdout, exit codes, or other data recorded during the test

Process-1 Under Test

Process-1 Shutdown

Process-2 Under Test

Process-2 Shutdown

Process-n Under Test

Process-n Shutdown

Start Launch
Description

Start Tests

Tests End. Shutdown
Launch Description

Start post-shutdown
Tests

Tests End

Using the launch_testing API

- Auto-generate test cases from documentation
 - Check that launch files in documentation continue to work as documented
 - Check that process arguments and values continue to work as documented
 - Check that documented topics are present in a launched system
 - Check that output generated by processes matches what's in the documentation
- Auto-generate tests that always run for every process tested automatically
 - Check output for errors
 - Check exit codes of all processes
- Automatically remap topics and insert nodes that fuzz the data before republishing, or drop messages

Possible Future Development

- Add ROS 1 style test processes
 - Run *gtest*s in a separate process
 - Run *pytest*s in a separate process
 - Run an arbitrary process that can pass/fail based on an exit code
- Include tests in the launch description
 - These tests could easily introspect the launch context to help test the launch description itself
- *rosv* integration to record data for analysis in post-shutdown tests

Example: Launch Test

Part 1/3

Package: launch/launch_testing/examples/good_proc.test.py

```
$ # can be run with:
```

```
$ launch_test launch_testing/examples/good_proc.test.py
```

```
def generate_test_description():
    return launch.LaunchDescription([
        launch.actions.ExecuteProcess(
            cmd=[path_to_process],
        ),

        # Start tests right away - no need to wait for anything in this example.
        # In a more complicated launch description, we might want this action happen
        # once some process starts or once some other event happens
        launch_testing.actions.ReadyToTest()
    ])
```

Example: Launch Test (con't)

Part 2/3

Active test

Inherits from
`unittest.TestCase`

*# These tests will run concurrently with the test in process. After all these tests are done,
the launch system will shut down the processes that it started up*

```
class TestGoodProcess(unittest.TestCase):
```

`ProcInfoHandler`
object

`IOHandler`
object

```
def test_count_to_four(self, proc_info, proc_output):
```

*# This will match stdout from any process. In this example there is only one process
running*

```
proc_output.waitFor('Loop 1', timeout=10)
```

```
proc_output.waitFor('Loop 2', timeout=10)
```

```
proc_output.waitFor('Loop 3', timeout=10)
```

```
proc_output.waitFor('Loop 4', timeout=10)
```

Waits for a particular
output on `proc_info`

Example: Launch Test (con't)

Part 3/3

Post Shutdown tests

Decorated with
`post_shutdown_test`
descriptor

Inherits from
`unittest.TestCase`

These tests will run after with the test in process is shut-down.

@launch_testing.post_shutdown_test()

class TestProcessOutput(unittest.TestCase):

def test_exit_code(self, proc_info, proc_output):

Check that all processes in the launch (in this case, there's just one) exit
with code 0

launch_testing.asserts.assertExitCodes(proc_info)

Asserts that the specified
process exited with a
particular exit code.

def test_out_of_order(self, proc_info, proc_output):

This demonstrates that we notice out-of-order IO

with self.assertRaisesRegex(AssertionError, "Loop 2 not found"):

with assertSequentialStdout(proc_output, <process>) as cm:

cm.assertInStdout('Loop 1')

cm.assertInStdout('Loop 3')

cm.assertInStdout('Loop 2') # This should raise

Asserts that `stdout`
was seen in a
particular order.

Asserts that a message
is found in the `stdout`
of the process

Using CMake to run launch_test

- Declare a dependency on *launch_testing_ament_cmake* in *package.xml*

```
<test_depend>launch_testing_ament_cmake</test_depend>
```

- In *CMakeLists.txt* file, add

```
find_package(launch_testing_ament_cmake)
add_launch_test(test/name_of_test.test.py)
```

- Optionally, arguments can also be passed to the tests:

```
add_launch_test(
  test/test_with_args.test.py
  ARGS "arg1:=foo"
)
```

Launch arguments to
be passed to the
launch test

Live Demo: Launch Test

Quick demonstration of launch test

Documentation and the ROS Buildfarm

Documentation:

ros2 / launch

<> Code

🔔 Issues 24

🔗 Pull requests 2

🛡 Security

📊 Insights

Branch: dashing

launch / launch_testing /

Create new fileFind fileHistory

This branch is 15 commits ahead, 54 commits behind master.

🔗 Pull request📄 Compare

nuclearsandwich 0.8.6

Latest commit 4a3aad9 25 days ago

..

example_processes	Fix proc lookup for processes with multiple command-line arguments (#229)	4 months ago
examples	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
launch_testing	[Dashing] Restore support for Python 3.5 (#324)	27 days ago
resource	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
test/launch_testing	Fix proc lookup for processes with multiple command-line arguments (#229)	4 months ago
CHANGELOG.rst	0.8.6	25 days ago
README.md	Use --isolated if no ROS_DOMAIN_ID is set to help parallel testing (#251)	4 months ago
package.xml	0.8.6	25 days ago
pytest.ini	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
setup.cfg	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
setup.py	0.8.6	25 days ago

📖 README.md

launch_testing

This tool is a framework for launch integration testing. For example:

- The exit codes of all processes are available to the tests.
- Tests can check that all processes shut down normally, or with specific exit codes.
- Tests can fail when a process dies unexpectedly.
- The stdout and stderr of all processes are available to the tests.
- The command-line used to launch the processes are avilalbe to the tests.
- Some tests run concurrently with the launch and can interact with the running processes.

Quick start example

Start with the `launch_testing` example `good_proc.test.py`.

Run the example by doing:

```
launch_test launch_testing/examples/good_proc.test.py
```

Example packages using *launch_testing* in ROS Buildfarm:

ros2 / launch

<> Code

🔔 Issues 24

🔗 Pull requests 2

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launch / launch_testing / test / launch_testing /

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🔗 Pull request📄 Compare

pbaughman and clalancette Fix proc lookup for processes with multiple command-line arguments (#229 ...)

Latest commit 1e3e2a9 on Jun 10

..

legacy	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
test_assert_exit_codes.py	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
test_copyright.py	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago
test_domain_coordinator.py	Merge apex_launchtest functionality into launch_testing (#215)	5 months ago

- https://github.com/ros2/rcutils/blob/dashing/test/test_logging_output_format.py
- https://github.com/ros2/rcl/blob/dashing/rcl/test/rcl/test_two_executables.py.in
- https://github.com/ros2/demos/blob/dashing/demo_nodes_cpp/test/test_executables_tutorial.py.in

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