

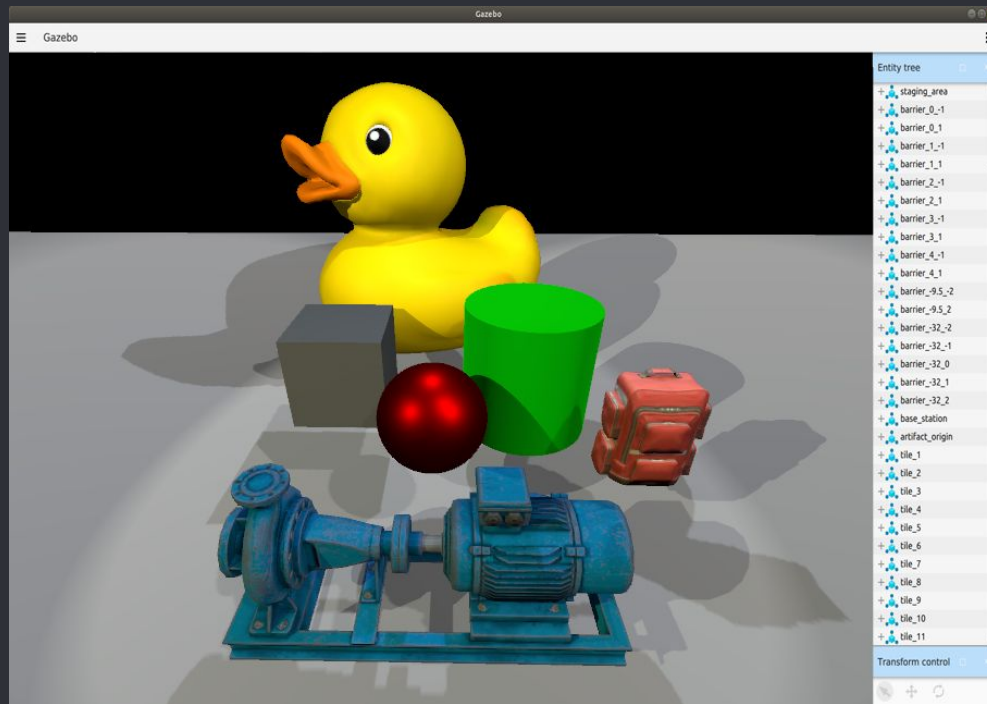
# How to Achieve Realistic Visuals in Ignition Gazebo

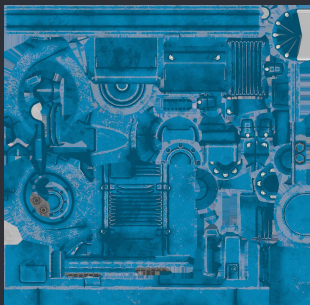
Cole Biesemeyer



This research was developed with funding from the Defense Advanced Research Projects Agency (DARPA). The views, opinions, and/or findings expressed are those of the author and should not be interpreted as representing the official views or policies of the Department of Defense or the U.S. Government. Distribution A - Approved for Public Release, Distribution Unlimited

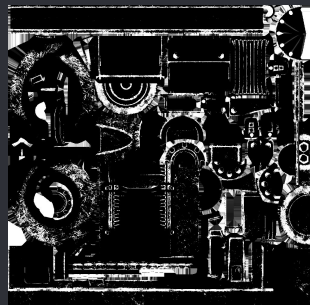
# Ignition Gazebo





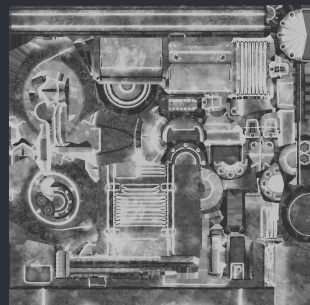
Albedo

+



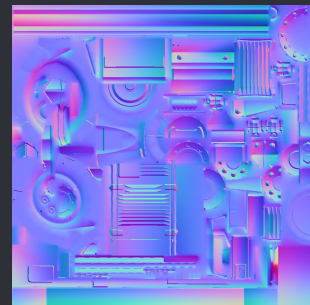
Metalness

+



Roughness

+

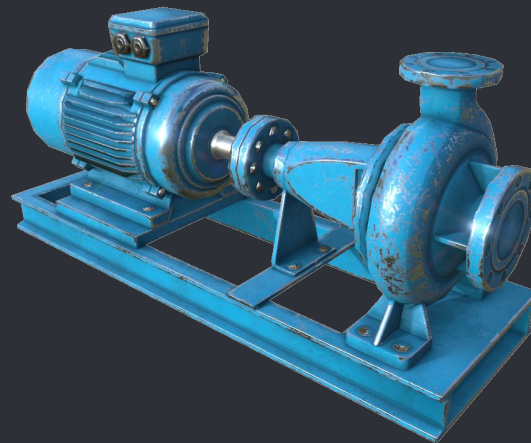


Normal

+



=



## ● What is Physically Based Rendering? (PBR)

### ● Gazebo Classic



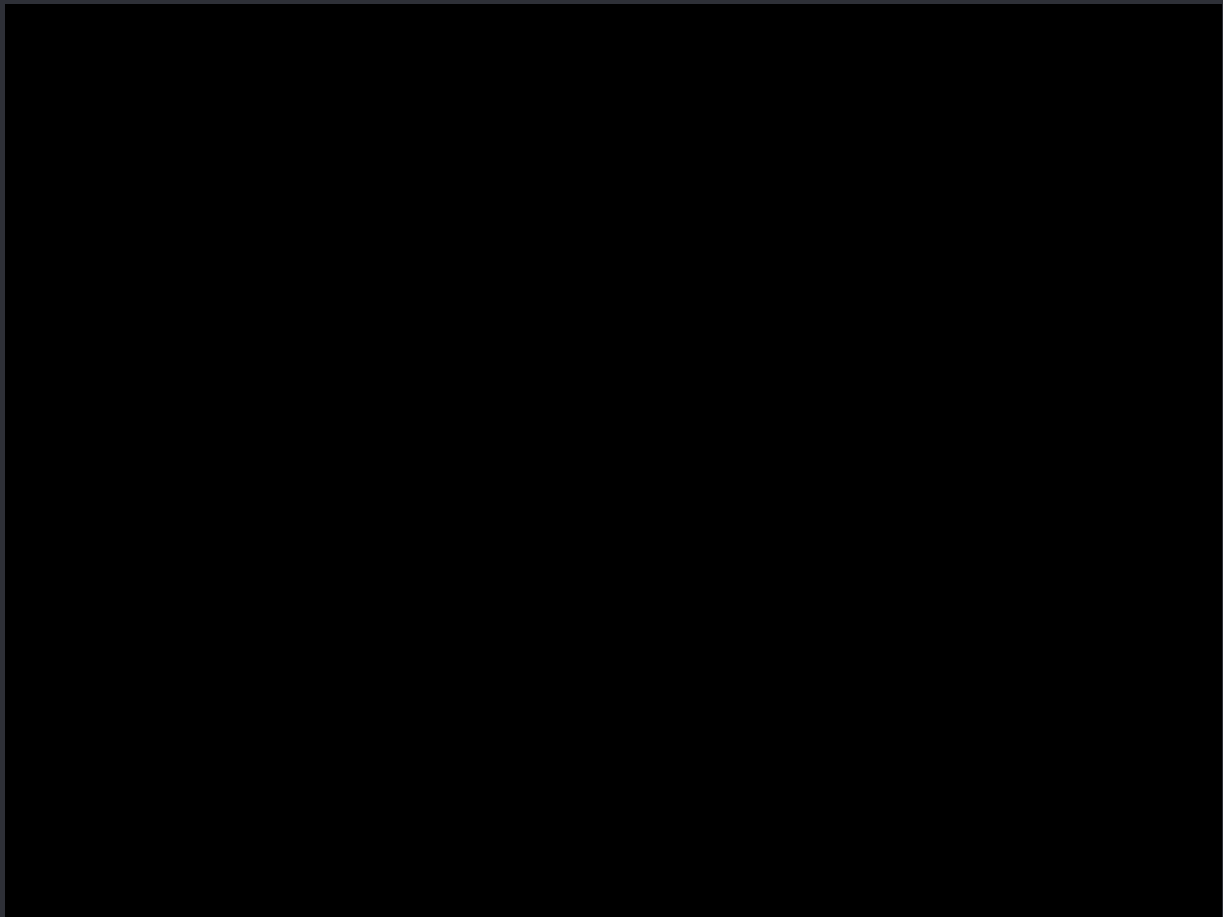
- Single color map
- No reflections
- Single surface type

### Ignition Gazebo



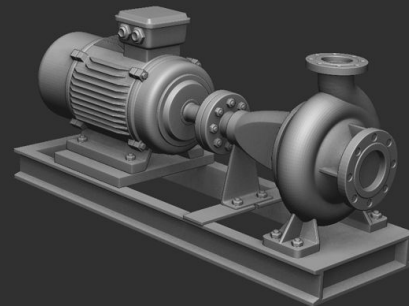
- Multiple maps to control lighting
- Surface accurately reflects light
- Multiple surface types on a single model





## ● High Resolution Source Models

- Standard workflow for creation of 3d assets.
- Allows for optimization at any level.
- Realistic, detailed assets.



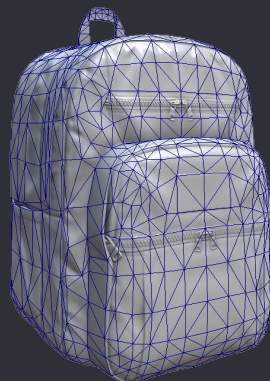
## ● Procedural texturing

- Change resolution without quality loss
- Change look of models quickly
- Consistent look across models using presets and material libraries

## PBR Workflow



High Polygon Count



Low Polygon Count



Final Textured Model



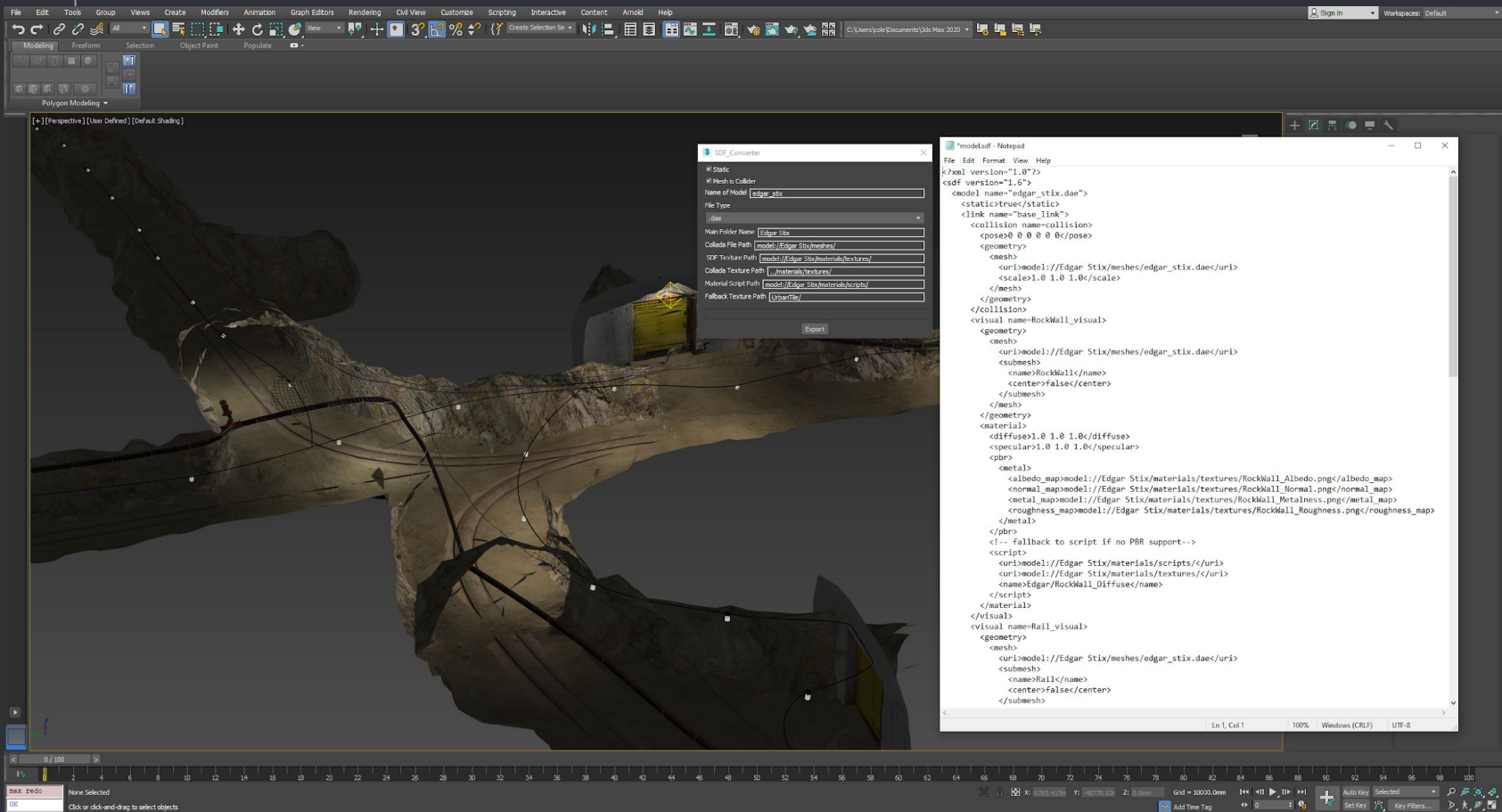
- Why is PBR important for robotics simulators?
  - Improvements over Gazebo Classic.
  - Better for computer vision systems.
  - Brings Ignition Gazebo closer to the visual fidelity and workflow of modern game engines.

## What PBR is not,

- Lighting/shadows
- Image effects

- Using PBR for the DARPA Subterranean Challenge

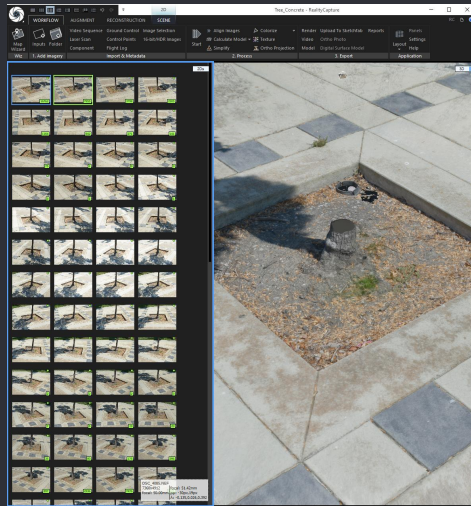




# • How to create better content, faster

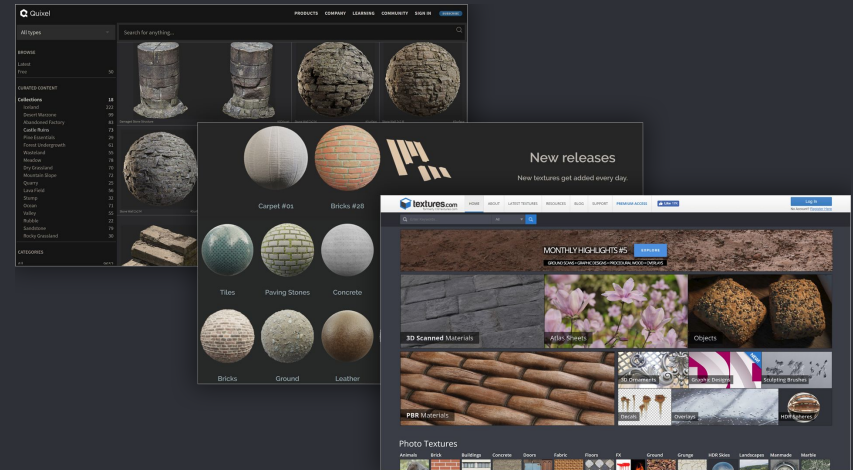
## Photogrammetry

The process of using 2d images to create 3d models of real life objects.



## Asset libraries

Online collections of various textures and models that can be used as a starting point for quickly creating 3d environments.





A large, dimly lit underground tunnel with a curved track and a suspension bridge. The tunnel walls are made of rough, layered rock. A curved track runs along the bottom of the tunnel, and a suspension bridge with a blue cable and red railings spans across it. Several white lights are hanging from the ceiling.

## ● Photogrammetry

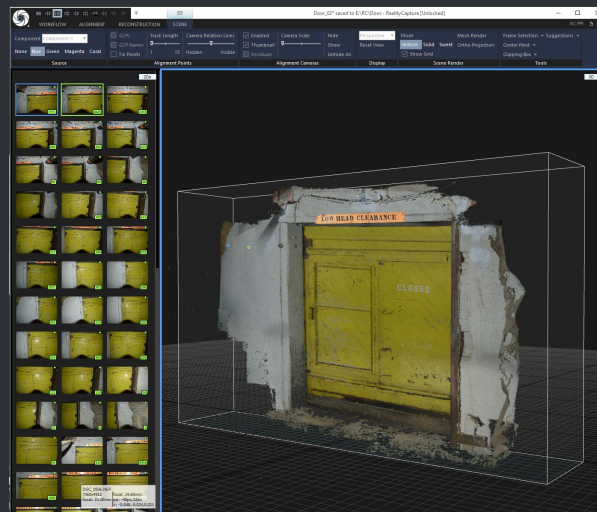


# ● PHOTOGRAMMETRY STEPS

○ *Take Photos*



*Process Photos*



*Optimize Model*



## ● ADVANTAGES OF PHOTOGRAMMETRY

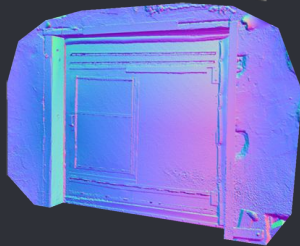
- 1:1 accuracy of real objects
- Faster than traditional methods
- Ultra high detail
- Cost
- Versatility



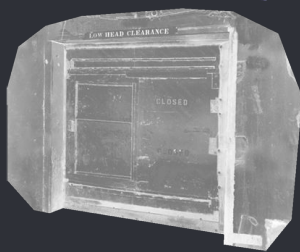
- How photogrammetry works with PBR



Albedo map  
from scan



Normal map  
from scan

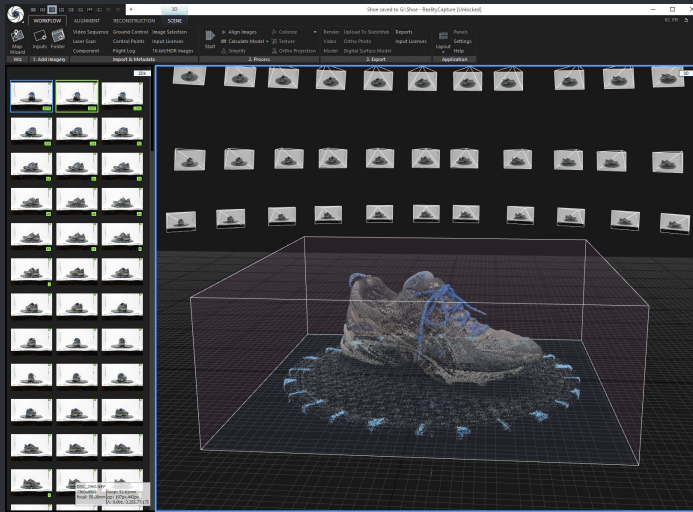


Roughness created  
By tweaking Albedo

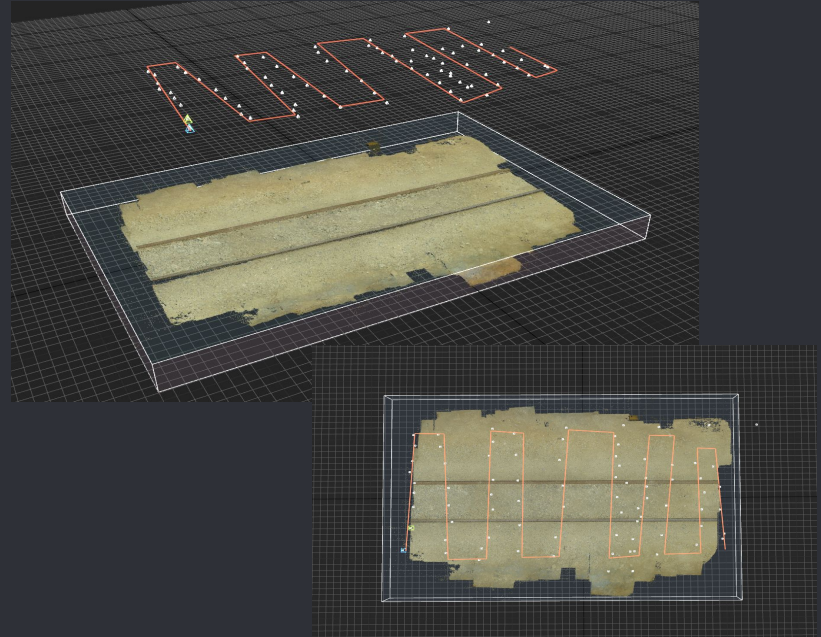


- Taking photos for photogrammetry

- Freestanding objects



- Flat surfaces





- Taking photos for photogrammetry

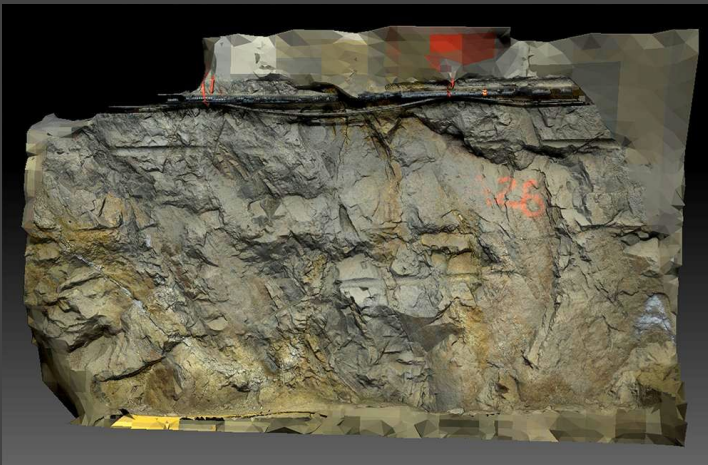
- Achieve neutral lighting

- Use a lightbox or studio setup
- Take photos on an overcast day
- Use delighting techniques

## Delighting Techniques

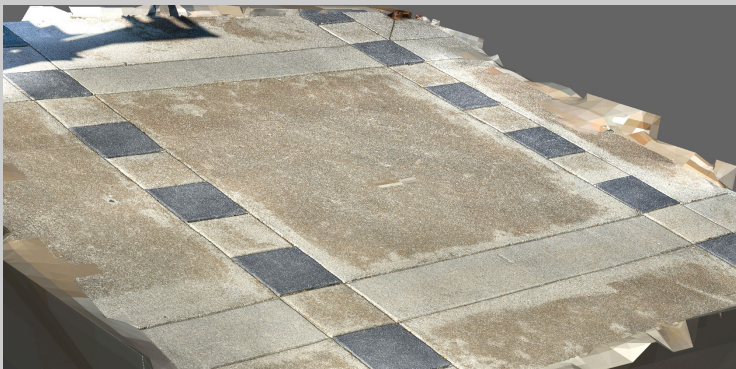
- Sometimes direct light is unavoidable
- Software to remove highlights and shadows
- Mix of software and manual input







DEFENSE  
INNOVATION UNIT





## ● Taking photos for photogrammetry

### ○ Hardware

- Nikon D800
- Tripod
- Remote Shutter

### Small object setup

- Lightbox
- Turntable

### Software

- Reality Capture



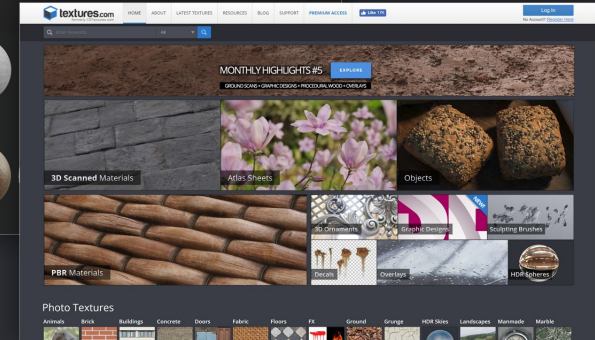
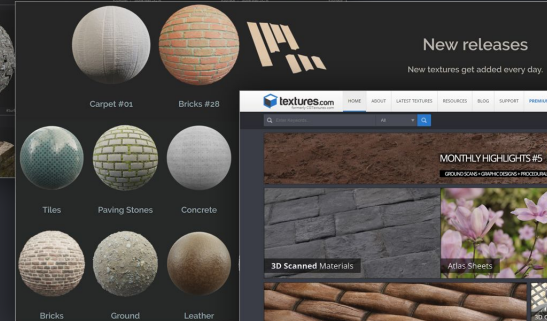
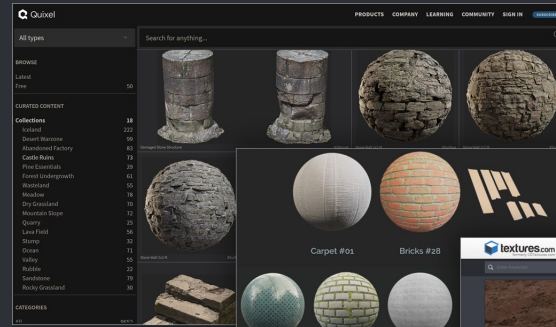
# RealityCapture



# Asset Libraries

A resource for finding finished assets

- Textures
- Models
- Animated characters
- UI Elements
- Audio



# What to look for when choosing models from a asset library

- Curated assets
- Assets from the same artist
- Real time engine marketplaces
- Level of Detail
- Licensing restrictions



- What they aren't good for
  - Projects that have a very large scope.
  - Projects with very specific needs.
  - Projects that require accuracy of an exact real life location.



## Looking outside the robotics community for 3D content creators

How a dedicated content creator can increase the visual fidelity of your projects.

# ● CONTENT CREATORS FOR ROBOTICS PROJECTS

## ○ What a content creator offers

- Knowledge of 3D rendering.
- How to get the most out of all assets.
- A creative perspective on virtual projects.
- Ensure projects are well optimized for real time performance.
- Faster Development.
- Create high fidelity objects for robots to interact with.
- Create and manage large scale 3d environments.

## Where to look:

- Video Game industry
- VFX industry
- Architectural industry
- Studios for hire
- Universities

# Thank you!

Contact: Cole@OpenRobotics.org

## Resources

- <https://ignitionrobotics.org/home>
- <https://www.darpa.mil/program/darpa-subterranean-challenge>
- [https://unity3d.com/files/solutions/photogrammetry/Unity-Photogrammetry-Workflow\\_2017-07\\_v2.pdf](https://unity3d.com/files/solutions/photogrammetry/Unity-Photogrammetry-Workflow_2017-07_v2.pdf)