

- ▶ **Service Robotics Modules**
- ▶ **meet PILZ at the ROS-Industrial booth**

- ▶ PRBT manipulator module with ros\_canopen JointTrajectory-interface for direct control
- ▶ ROSIN-FTP: industrial trajectory generation (no vendor-specific robot-controller!)



- ▶ Pilz offers Service Robotics Modules

- ▶ Future:  
ROS-Integration of other PILZ components
- ▶ Check out the OpenSource packages:  
[wiki.ros.org/pilz\\_robots](http://wiki.ros.org/pilz_robots)