

Vehicle and city simulation with Gazebo and ROS

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Background

Community interest in autonomous vehicle development

Resources for vehicle and city simulation

Vehicle



Environment



Plugin



Road network



City



Prius Challenge

Compete for best Fuel Economy
20 teams, 9 laps, <45min
Goal: 100+ MPG (2.35 L/100km)

Prius Hybrid
Sonoma Raceway



Demo

Prius Hybrid Model



Ackerman steering

Rolling resistance

- Modeled as joint friction torque

Aerodynamic drag

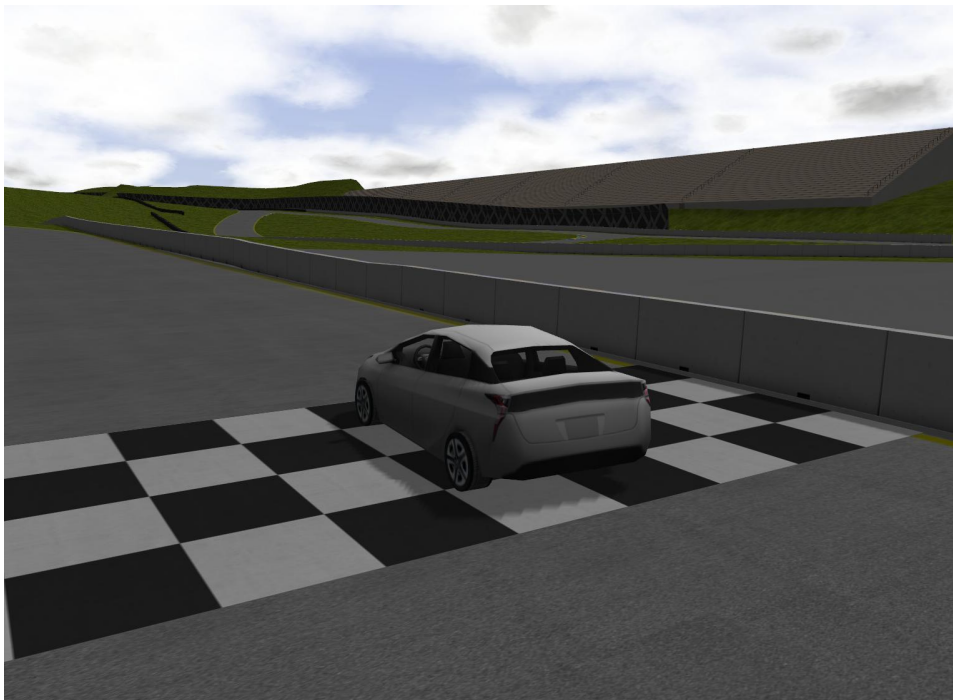
- Modeled as force acting on CoM

Suspension

- Allowed axle to roll for slopes and banked turns

Powertrain model

- State machine determines combination of engine and electric motor



https://github.com/osrf/collaboration/blob/new_data/hyperdrive_json/hyperdrive_json.ipynb

ROS + Gazebo Car Demo



ROS Kinetic

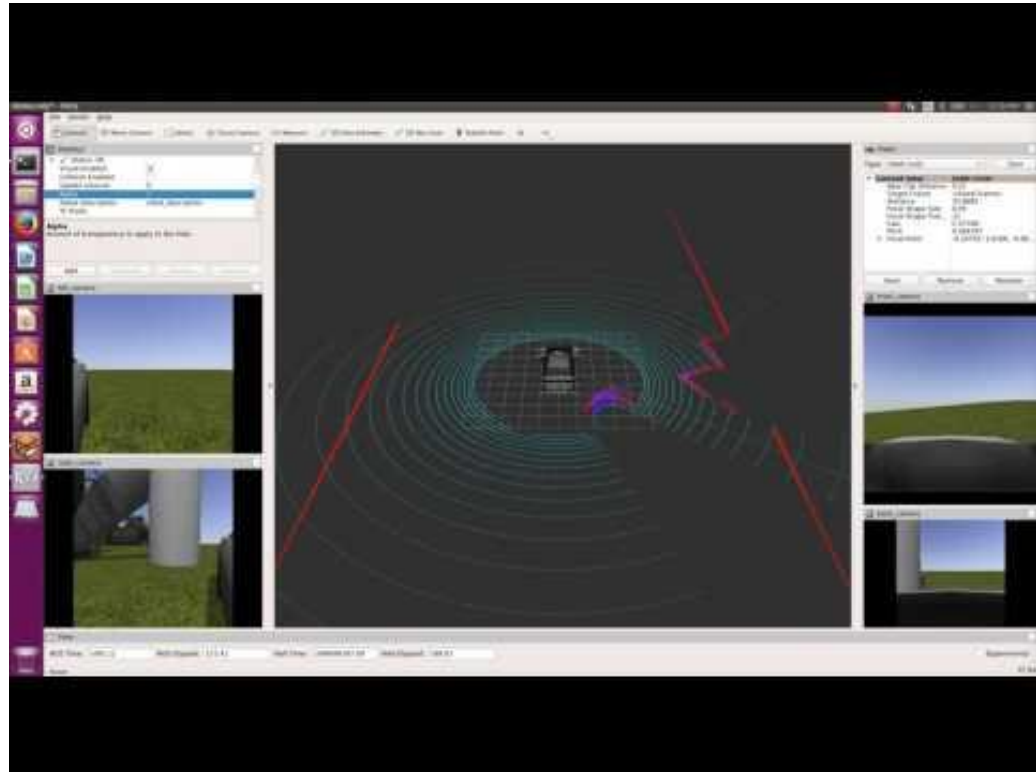
Prius description URDF

- Planar Lidar
- Block Lidar
- Sonar
- Cameras

Control msg:

- Throttle, brake, steer, gear

Mcity test facility



Deep Learning + Self Driving Car Demo

Nvidia End to End Learning Model

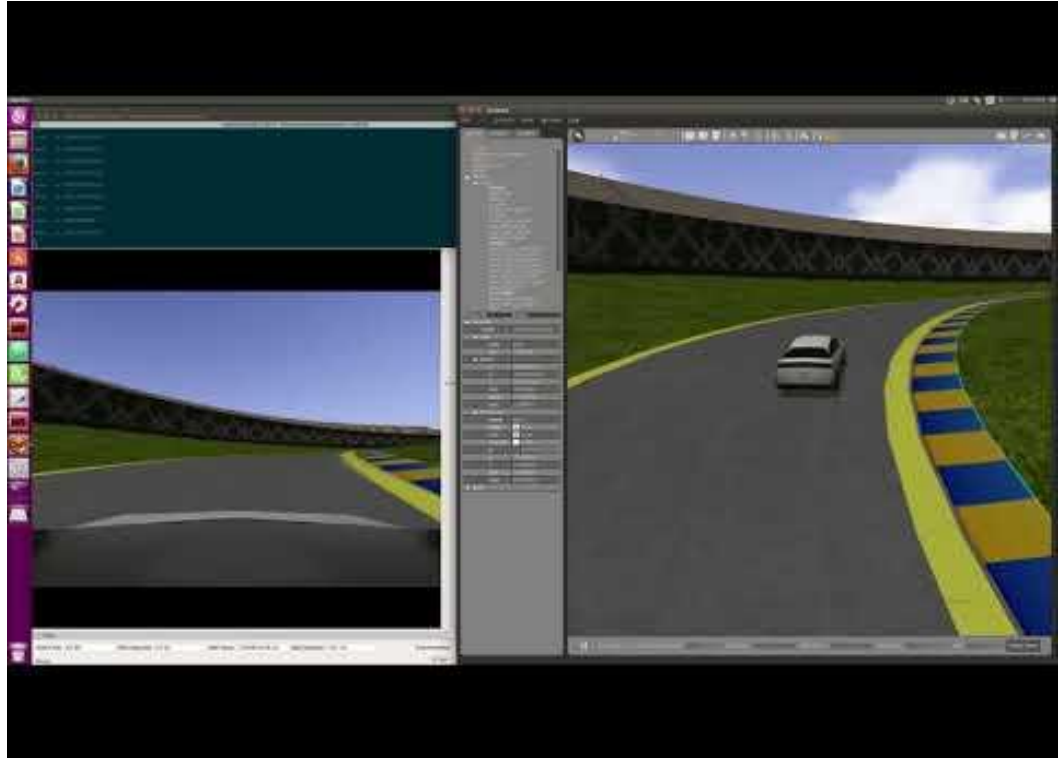
Two Nodes:

Driving

Object Detection

https://github.com/osrf/yolo_object_detector

https://github.com/osrf/tensorflow_object_detector



Ignition RNDF (Route Network Definition File)



C++ library for handling RNDF files

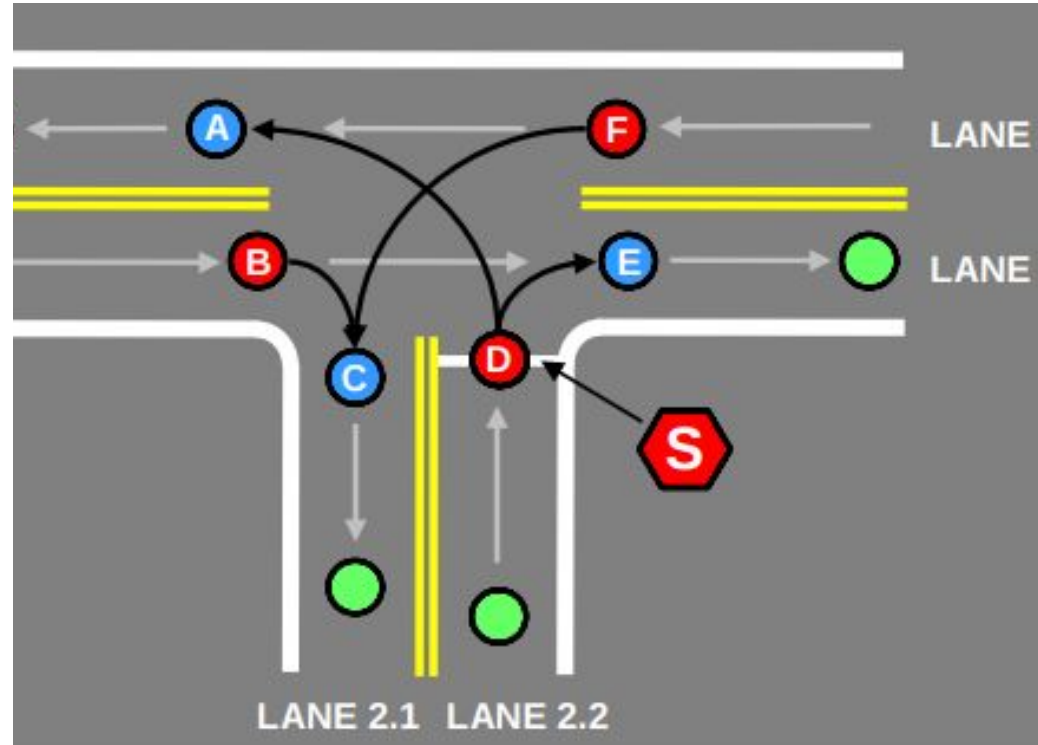
What is a road network definition?

Why do we need it?

Why RNDF (and not OpenDRIVE)?

Ignition RNDF features

- C++11, cross-platform, Apache 2
- In-memory representation of RNDF



Terminus

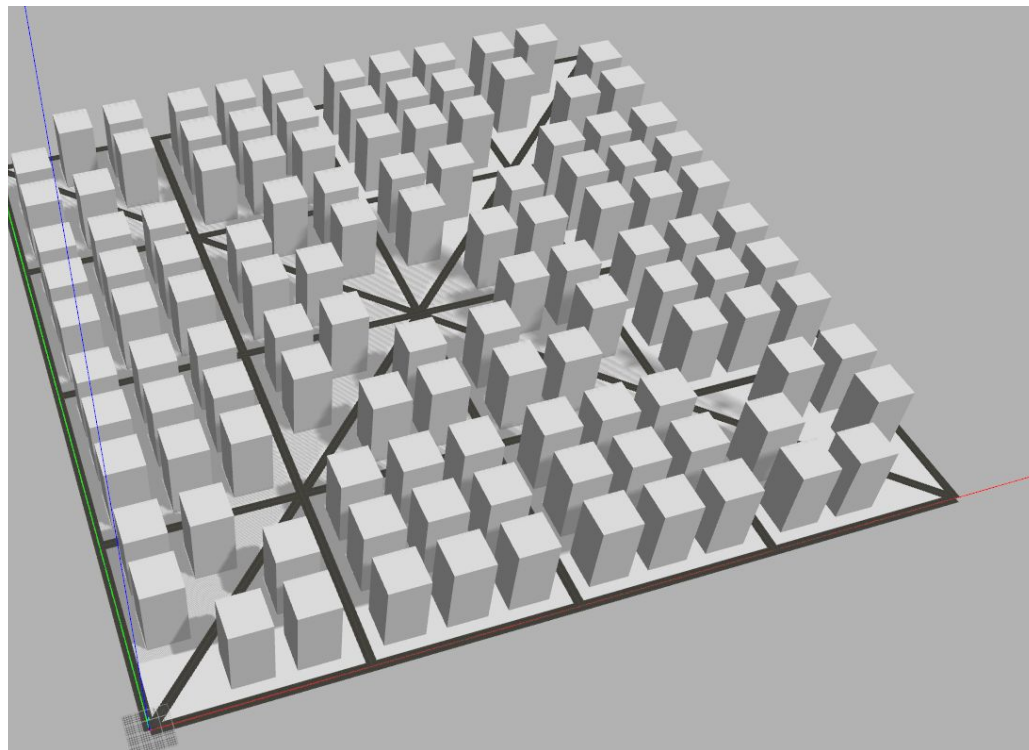


Generate or import simulated cities

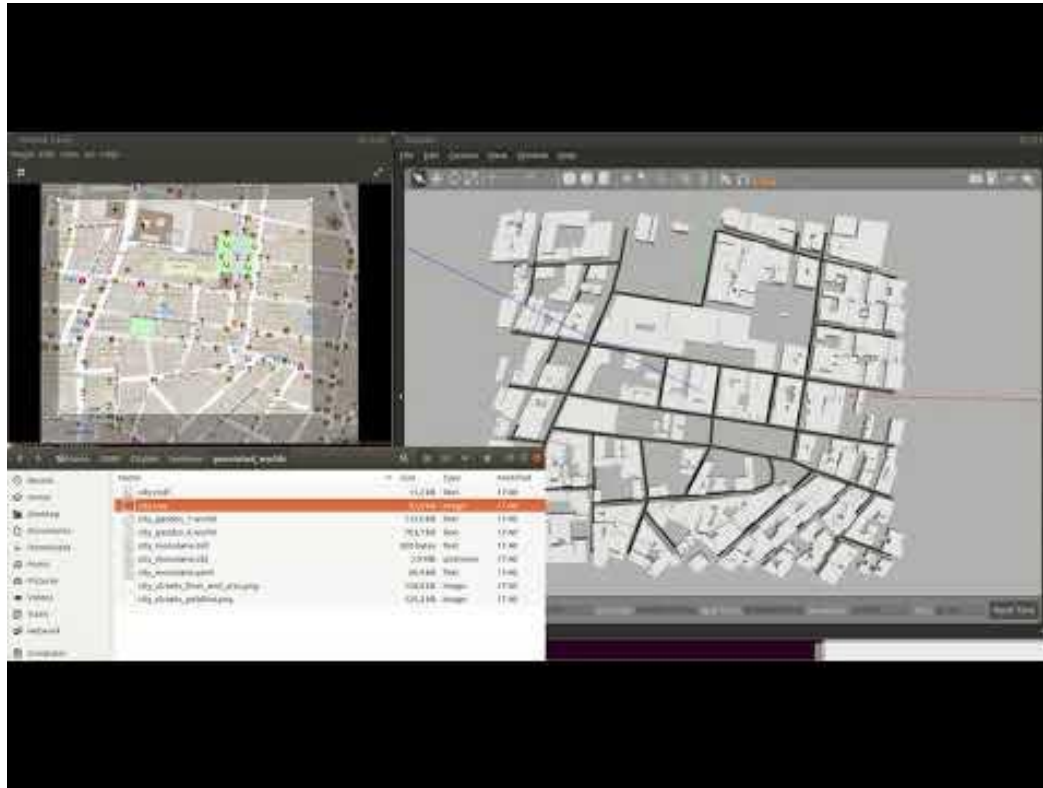
Why is this useful?

Overview

- Procedural cities
- Import data from OpenStreetMap
- Roads + buildings
- Multiple formats
- Gazebo & Drake



Terminus



Summary

Vehicle model: Prius



Environment models: Mcity, Sonoma Raceway



Plugin: Powertrain model



Road networks: Ignition RNDP



Cities: Terminus



Future ideas

Vehicle models: bikes, trucks, sidecars, trailers, RVs

Environment models: curated environments with interesting features

Plugins: Traffic, pedestrians, weather

Sensors: Radar

Road networks: More formats, common API

Cities: More artificial cities

Thanks

Questions?

