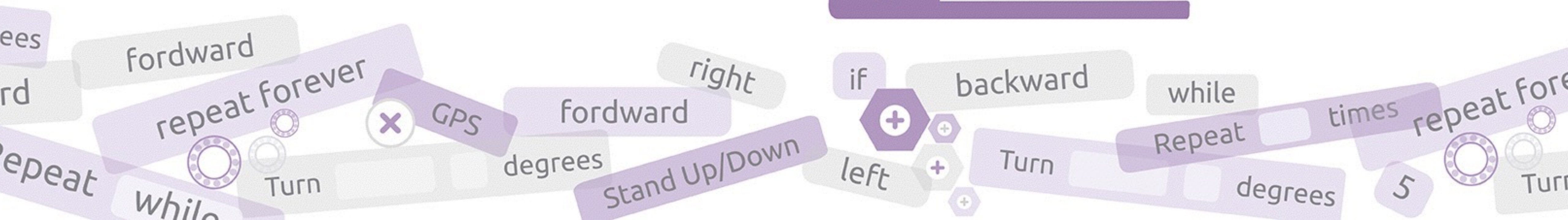
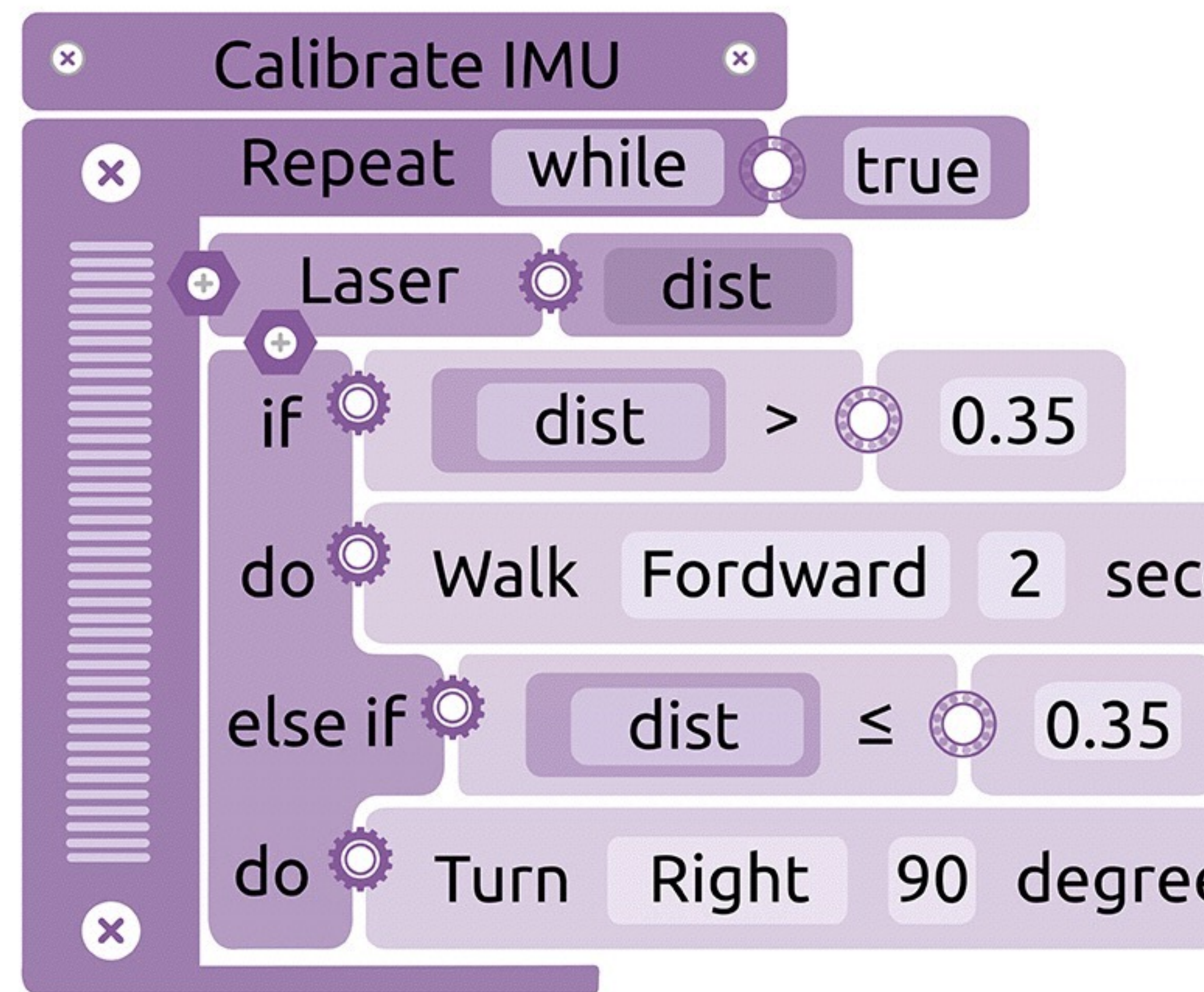
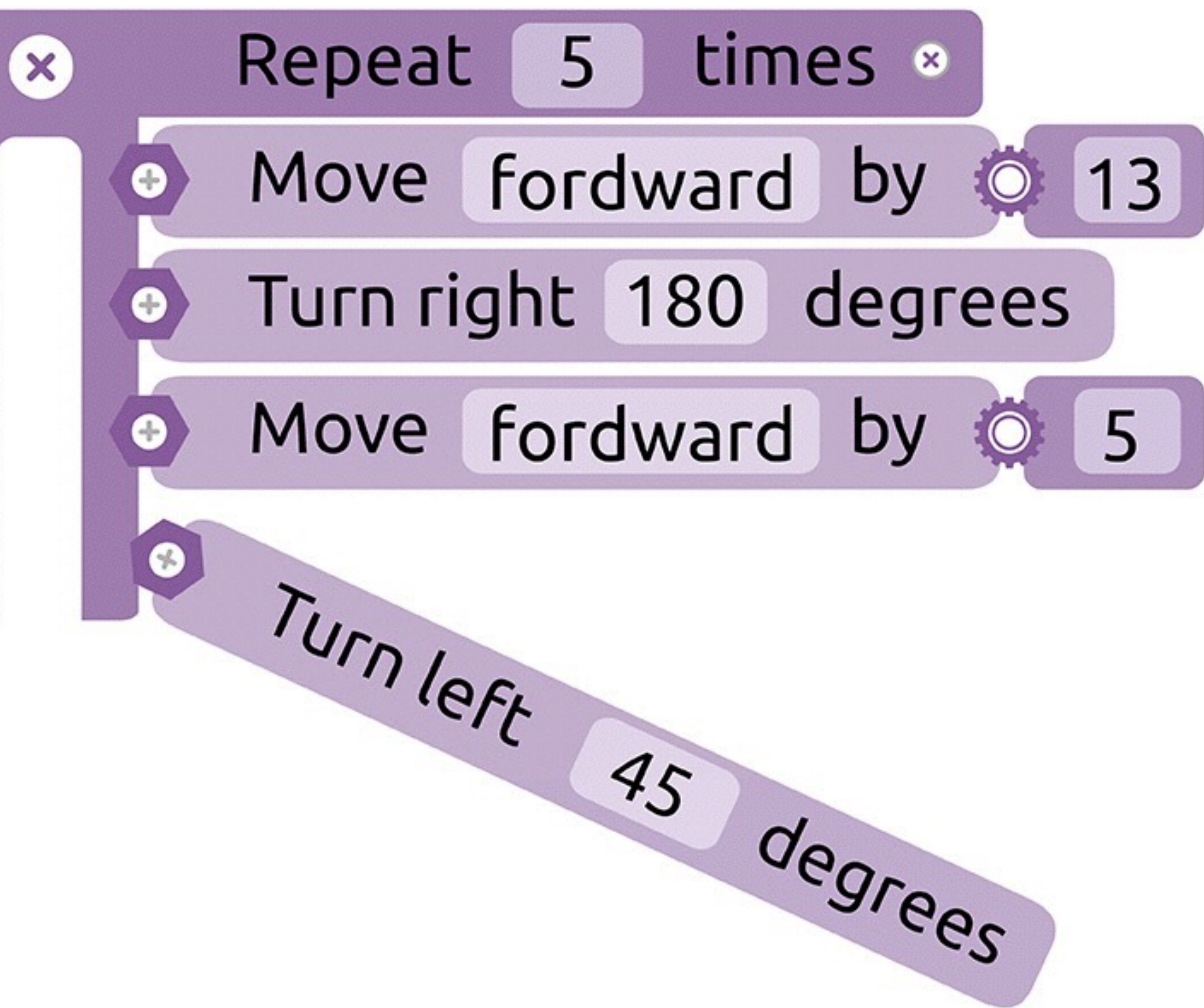




The robot_blockly package: programming ROS with blocks

Erle Robotics

Alejandro Hernández



What is Scratch?

Scratch is a visual programming language

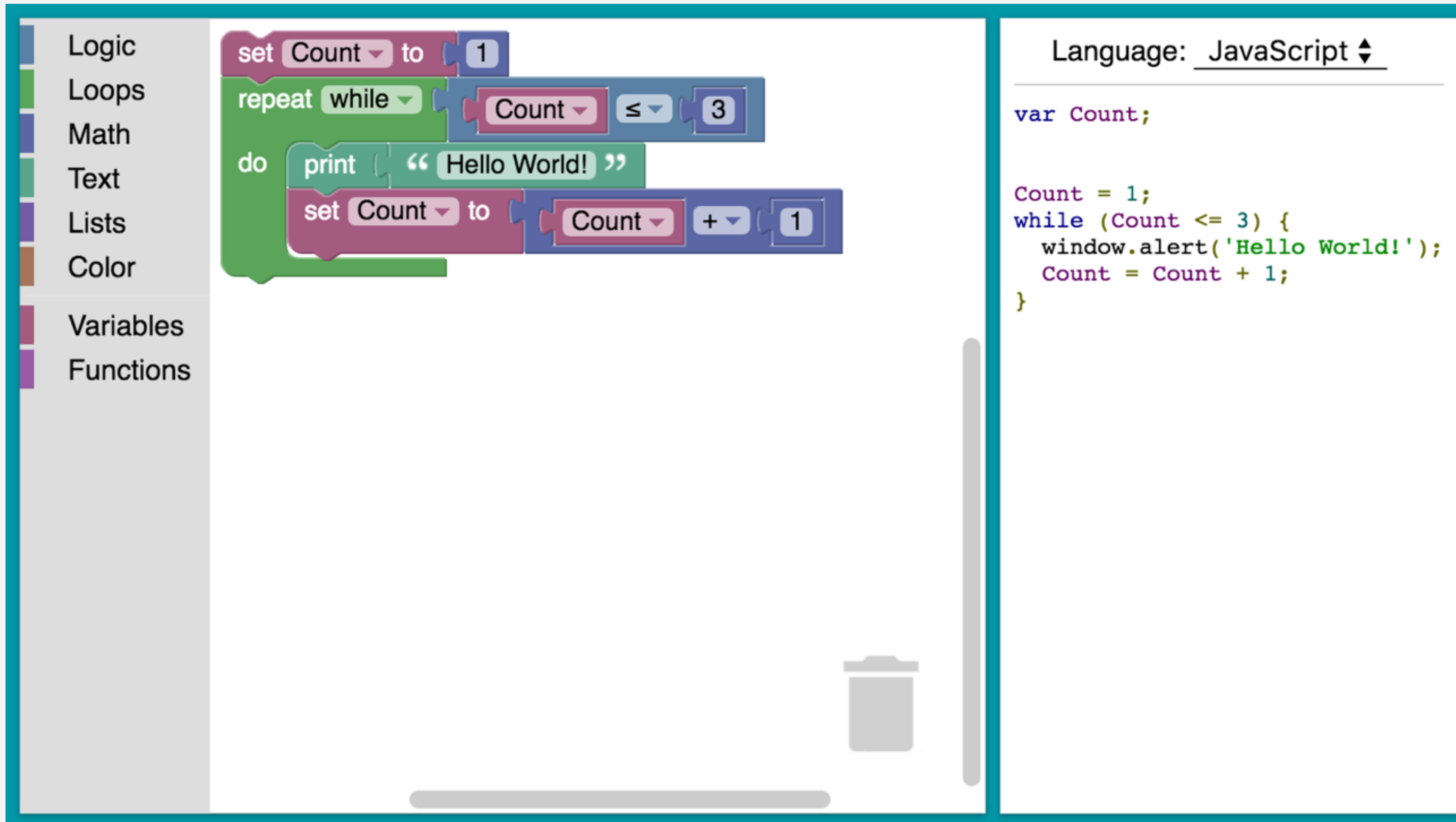
Scratch was created in 2003 as an educational programming language by MIT that allows learning to program using blocks.

Scratch is primarily designed for 8 to 16 year olds, it is also used by people of all ages, including younger children with their parents.



Initiated in 2003, has received generous support from the National Science Foundation (grants 0325828, 1002713, 1027848, 1019396), Intel Foundation, Microsoft, MacArthur Foundation, LEGO Foundation, Code-to-Learn Foundation, Google, Dell, Fastly, Inversoft, and MIT Media Lab research consortia

Blockly



The image shows the Blockly web editor interface. On the left is a category menu with options: Logic, Loops, Math, Text, Lists, Color, Variables, and Functions. The main workspace contains a script with the following blocks: a 'set Count to 1' block, a 'repeat while' loop block with 'Count' as the condition and '3' as the limit, and a 'do' block containing a 'print "Hello World!"' block and a 'set Count to Count + 1' block. On the right, the 'Language: JavaScript' dropdown is selected, and the corresponding JavaScript code is displayed in a text area.

```
var Count;

Count = 1;
while (Count <= 3) {
  window.alert('Hello World!');
  Count = Count + 1;
}
```

<https://github.com/google/blockly>

Mitch Resnick

“We shouldn’t think about young people as digital natives”

Mitch Resnick. Director of the Lifelong Kindergarten group at the MIT Media Lab.



Young people have a lot experience at interacting with new technologies but **lot less at creating and expressing themselves with new technologies.**

Mitch Resnick



... it's almost as if they could
read but not write

Mitch Resnick

The third language

Should Computer Coding Be Considered A Foreign Language in School? Some Say Yes

by ALLISON SLATER TATE

Why Estonia Has Started Teaching Its First-Graders To Code



Parmy Olson, FORBES STAFF ✓

I cover agitators and innovators in mobile.

[FULL BIO](#) ✓

New York Mayor Michael Bloomberg takes coding course

🕒 8 March 2012 | [Technology](#)

New York Mayor Michael Bloomberg has resolved to take an online computer coding course.

The mayor is joining more than 180,000 people currently taking part in Code Year, a campaign to encourage more people to programme.

"My New Year's resolution is to learn to code with Codecademy in 2012!" he



New York Mayor Michael Bloomberg is learning to code


```

var iiObject = Class.create({
  initialize: function(pos, y){
    if (typeof(y) == 'undefined')
      this.pos = pos || new iiVec2();
    else this.pos = new iiVec2(pos,y);
    this.drawCenter = true;
  },
  setPos: function(v,y){
    if(typeof(y) == 'undefined')
      this.pos = v;
    else {
      this.pos.x = v;
      this.pos.y = y;
    }
  },
  move: function(v,y){
    this.pos.add(v,y);
  },
  draw: function(ctx){
    if (this.drawCenter){
      //draw middle dot
      ctx.fillStyle = '#fff';
      ctx.fillRect(this.pos.x-2, this.pos.y-2, 4, 4);
    }
  }
});

var iiShape = Class.create(iiObject, {
  initialize: function($super, pos, y, vel, velY){
    $super(pos, y);
    if (typeof(velY) == 'undefined')
      this.vel = vel || new iiVec2();
    else this.vel = new iiVec2(vel,velY);
  },
  update: function($super, dt){
    if (typeof(this.drawables) != 'undefined')
      for (var i=0;i<this.drawables.length;i++){
        if (typeof(this.drawables[i].update) != 'undefined')
          if(!this.drawables[i].update())
            return false;
      }
    this.move(new iiVec2(this.vel.x*dt, this.vel.y*dt));
    if (typeof(this.torque) != 'undefined') this.rotation+=this.torque;
    if (this.bounds != null && ((this.bounds.top != null && this.pos.y <
      this.bounds.top) || (this.bounds.right != null && this.pos.x > this
      .bounds.right) || (this.bounds.bottom != null && this.pos.y > this
      .bounds.bottom) || (this.bounds.left != null && this.pos.x < this
      .bounds.left)))
      return false;
    return true;
  },
  draw: function($super, ctx){
    if (typeof(this.drawables) != 'undefined'){
      ctx.save();
      ctx.translate(this.pos.x, this.pos.y);
      if (typeof(this.rotation) != 'undefined')
        ctx.rotate(this.rotation);
      for (var i=0; i<this.drawables.length; i++)
        this.drawables[i].draw(ctx, this.pos);
      ctx.restore();
    }
    if (this.drawBox){
      //draw outside border
      ctx.strokeStyle = '#fff';
      ctx.strokeRect(this.left(), this.top(), this.width, this.height);
    }
    $super(ctx);
  },
  addDrawable: function(drawable){
    if (typeof(this.drawables) == 'undefined')
      this.drawables = [];
    var i=this.drawables.length;
    this.drawables[i] = drawable;
  }
});

```

```

function SpaceShooter(){
  var player;
  var playerHSpeed = 9;
  var playerVSpeed = 8;
  var playerMove = [0,0,0,0,0];
  var spaceDown = false;
  var backgroundSpeed = 18;

  var asteroidHealth = 4;

  var playerBullets = [];
  var asteroids = [];

  var score = 0;
  var scoreText;

  var backgroundSrcs = ['img/png/Background/starBig.png', '
    img/png/Background/starSmall.png', 'img/png/Background/speedLine.png',
    'img/png/Background/nebula.png'];

  var asteroidSrcs = ['img/png/meteorBig.png', 'img/png/meteorSmall.png'];

  var iio;
  this.init = function(iioController){
    iio = iioController;
    iio.setBGPattern('img/png/Background/backgroundColor.png');
    iio.createGroup('asteroids', 0);
    iio.createGroup('stars', -30);
    iio.createGroup('nebulas', -20);
    iio.createGroup('player', 10);
    iio.createGroup('player bullets', 10);
    iio.createGroup('laser flashes', 15);
    iio.runDebugger();

    var srcs = ['img/png/playerLeft.png','img/png/player.png','
      img/png/playerRight.png'];
    player = new iiBox(iio.canvas.width/2, iio.canvas.height-200, 0,0);
    player.addDrawable(new iiAnim(srcs, 0, 0, 1), true);
    iio.addToGroup('player', player, 10);
    //player.drawBox = true;

    runBgCreator(0, iio.canvas.height);

    iio.createGroup('UI', 30);

    scoreText = iio.addToGroup('UI', new iiText('Score: '+score, "30px
      Arial", 'black', iio.canvas.width-180, 40));

    setCollisionCallbacks();
  }
  this.resize = function(){
    scoreText.setPos(iio.canvas.width-180, 40);
  }
  var shootTimer = 20;
  var shootCount = 0;
  this.update = function(dt){
    updateBackground();
    updatePlayer();
    if (spaceDown && shootCount < 0){
      createBullet(player.left()+10, player.pos.y);
      createBullet(player.right()-8, player.pos.y);
      shootCount = shootTimer;
    }
    if (spaceDown) shootCount--;
    else shootCount-=4;
  }

  function setCollisionCallbacks(){
    iio.setCollisionCallback('player bullets', 'asteroids', function(bullet
      , asteroid){
      iio.addToGroup('laser flashes', new iiBox((bullet.pos.x+asteroid
        .pos.x)/2, (bullet.pos.y+asteroid.pos.y)/2, asteroid.vel.x,

```

```

var iiImage = Class.create(iiObject, {
  initialize: function($super, src, pos, y, size, h) {
    $super(pos, y);
    if (src instanceof Image) {
      this.img = src;
      this.width=size||this.img.width||0;
      this.height=h||size||this.img.height||0;
    }
    else{
      this.img = new Image();
      this.img.src = src;
      this.img.onload = function(){
        this.width=size||this.img.width||0;
        this.height=h||size||this.img.height||0;
      }.bind(this);
    }
  },
  draw: function(ctx, origin){
    ctx.save();
    ctx.translate(this.pos.x, this.pos.y);
    if (typeof(this.rotation) != 'undefined')
      ctx.rotate(this.rotation);
    ctx.translate(-this.width/2,-this.height/2);
    if (typeof(this.img) != 'undefined')
      ctx.drawImage(this.img, 0, 0, this.width, this.height);
    ctx.restore();
  },
  setSize: function(w,h){ this.width = w; this.height = h; }
});

var iiAnim = Class.create(iiImage, {
  initialize: function($super, srcs, pos, y, aIndex, w, h){
    aIndex = aIndex || 0;
    if (arguments.length > 0 && srcs instanceof Array)
      $super(srcs[aIndex], pos, y, w, h);
    else throw new Error('invalid image source array');
    this.imgs = [];
    for (var i=0;i<srcs.length;i++){
      this.imgs[i]=new Image();
      this.imgs[i].src=srcs[i];
    }
    this.imgIndex = aIndex;
  },
  update: function(dt){
    if (this.shrinking > 0)
      this.setSize(this.width*(1-this.shrinking), this.height*(1-this
        .shrinking));
    if (this.width > 0 && this.width < .1)
      return false;
    return true;
  },
  getWidth: function(i){
    if (typeof(i) == 'undefined')
      return this.imgs[this.imgIndex].width;
    else return this.imgs[i].width;
  },
  getHeight: function(i){
    if (typeof(i) == 'undefined')
      return this.imgs[this.imgIndex].height;
    else return this.imgs[i].height;
  },
  setImgIndex: function(i){
    this.imgIndex = i;
    this.img = this.imgs[i];
  },
  updateSize: function(w, h){
    switch(arguments.length){
      case 0: this.width = this.imgs[this.imgIndex].width;
        this.height = this.imgs[this.imgIndex].height;
        break;
      case 1: if (w instanceof iiVec2){
        this.width = w.x

```


By using **scratch**, people are able
to become **fluent with new**
technologies..., they are able to express
their ideas with them by **programming**.

Mitch Resnick

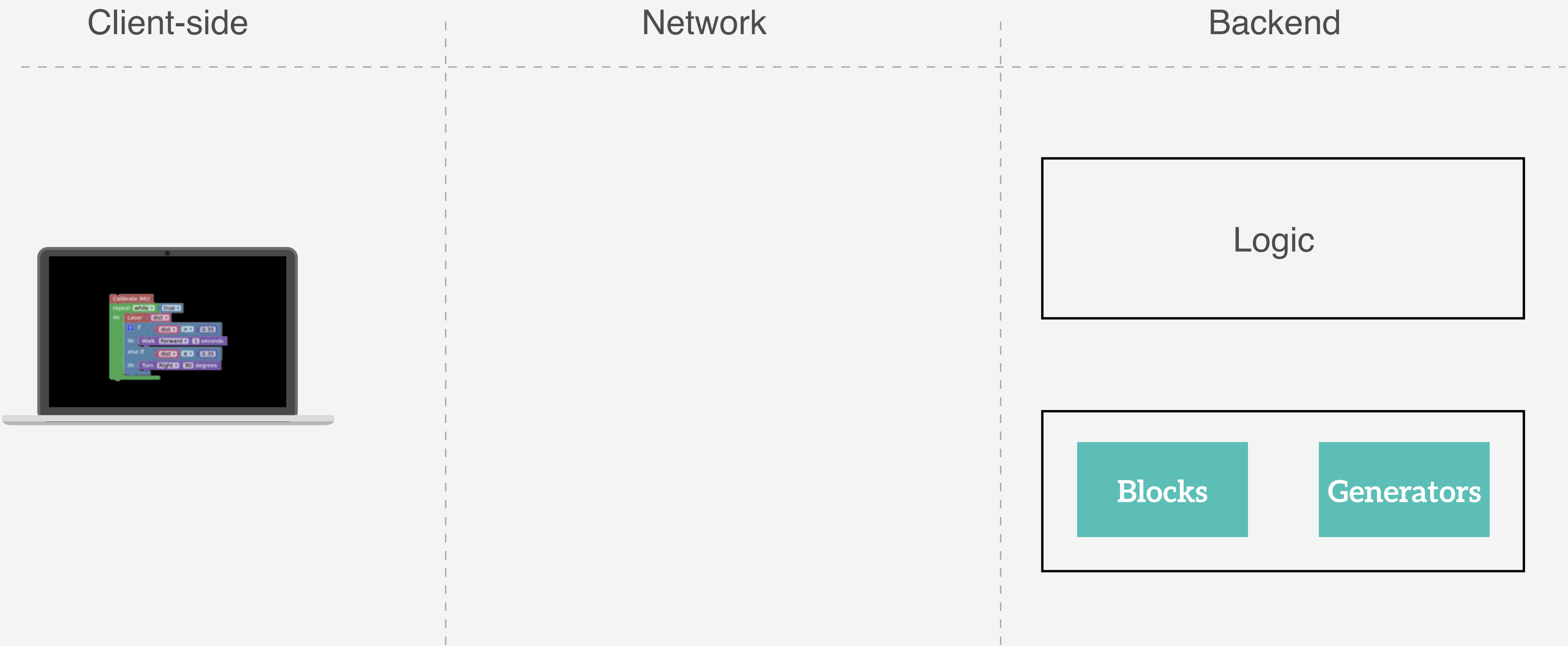
robot_blockly

The screenshot displays the robot_blockly web interface, which is powered by ROS. The interface is divided into several sections:

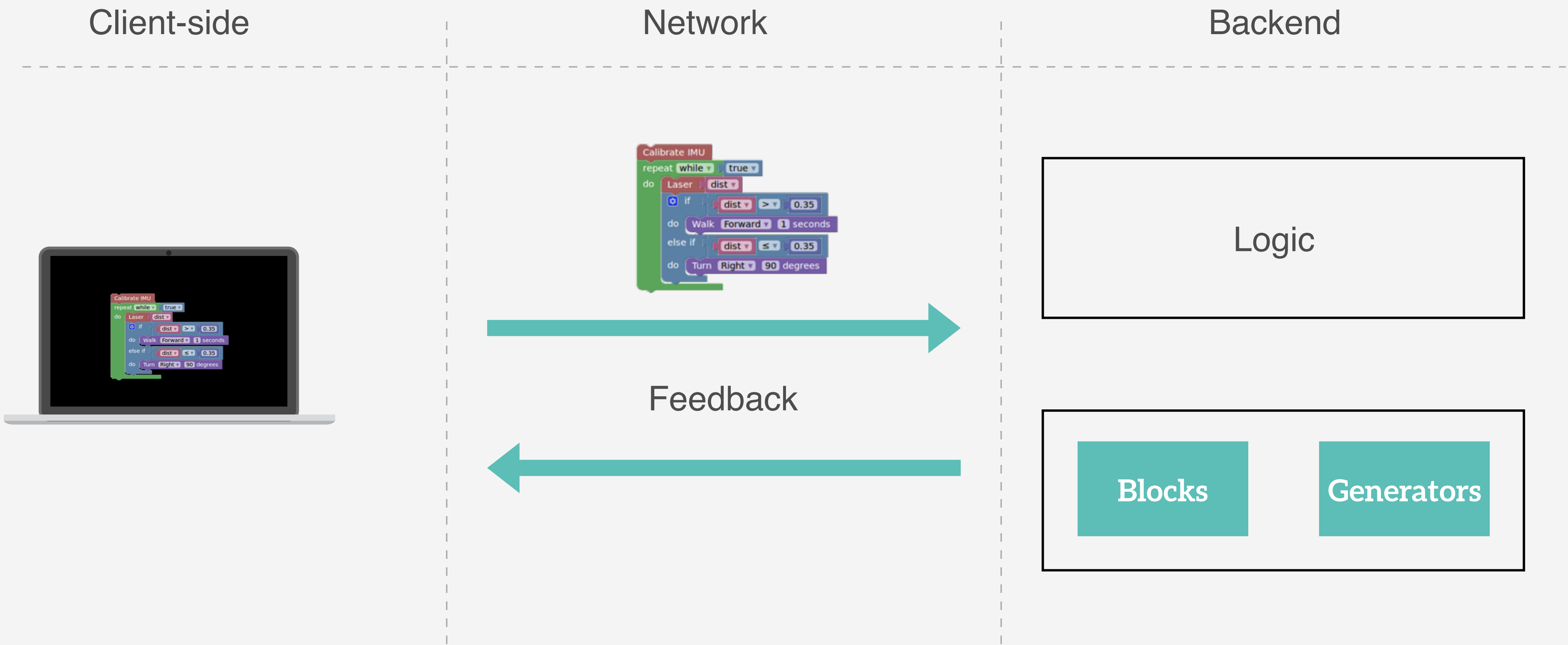
- Header:** The top bar features the "robot_blockly" logo, the text "powered by ROS", and the "Erle Robotics" logo.
- Left Sidebar:** Contains navigation options: "Builder" (selected), "Launch", "Load From File", "Save To File", "Clean workspace", "Python: 3 2", "Graph", and "Manual control".
- Block Categories:** A central column lists various block categories: Logic, Loops, Math, Lists, Variables, Functions, Code, and Control. Below these, specific robot models are listed: Erle-Spider (selected), Erle-Copter, Erle-HexaCopter, Erle-Rover, and Erle-Brain.
- Blockly Workspace:** The main area shows a script for a robot. The script starts with a "Stand up/down" block, followed by a "Walk Forward 1 seconds" block, and then two "Turn Left" blocks (one for 1 seconds and one for 90 degrees). A "Calibrate IMU" block is also present, followed by a "repeat while true" loop. Inside the loop, there is a "Laser dist" block, an "if dist > 0.35" condition leading to a "Walk Forward 1 seconds" block, and an "else if dist ≤ 0.35" condition leading to a "Turn Right 90 degrees" block.

https://github.com/erlerobot/robot_blockly

Architecture



Architecture





Structure

Create custom blocks

Blockly > Demos > Block Factory

Input
Field
Type
Colour

name block_type
inputs
automatic inputs
no connections
colour

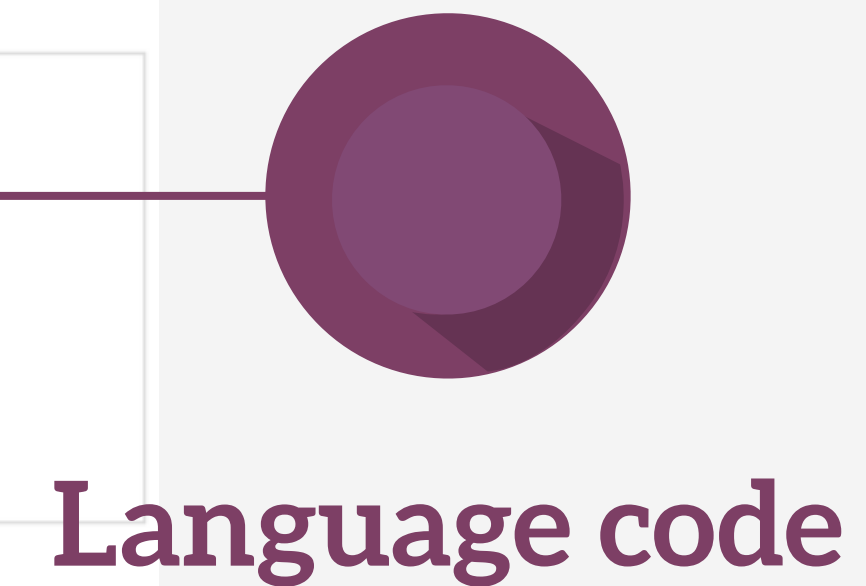
Preview: LTR

Language code: JavaScript

```
Blockly.Blocks['block_type'] = {  
  init: function() {  
    this.setTooltip('');  
    this.setHelpUrl('http://www.example.com/');  
  }  
};
```

Generator stub: Python

```
Blockly.Python['block_type'] = function(block) {  
  // TODO: Assemble Python into code variable.  
  var code = '...\n';  
  return code;  
};
```



Recommendations



Use `rospy.wait_for_message()` Be sure that you have received the data from a publisher in the code block.

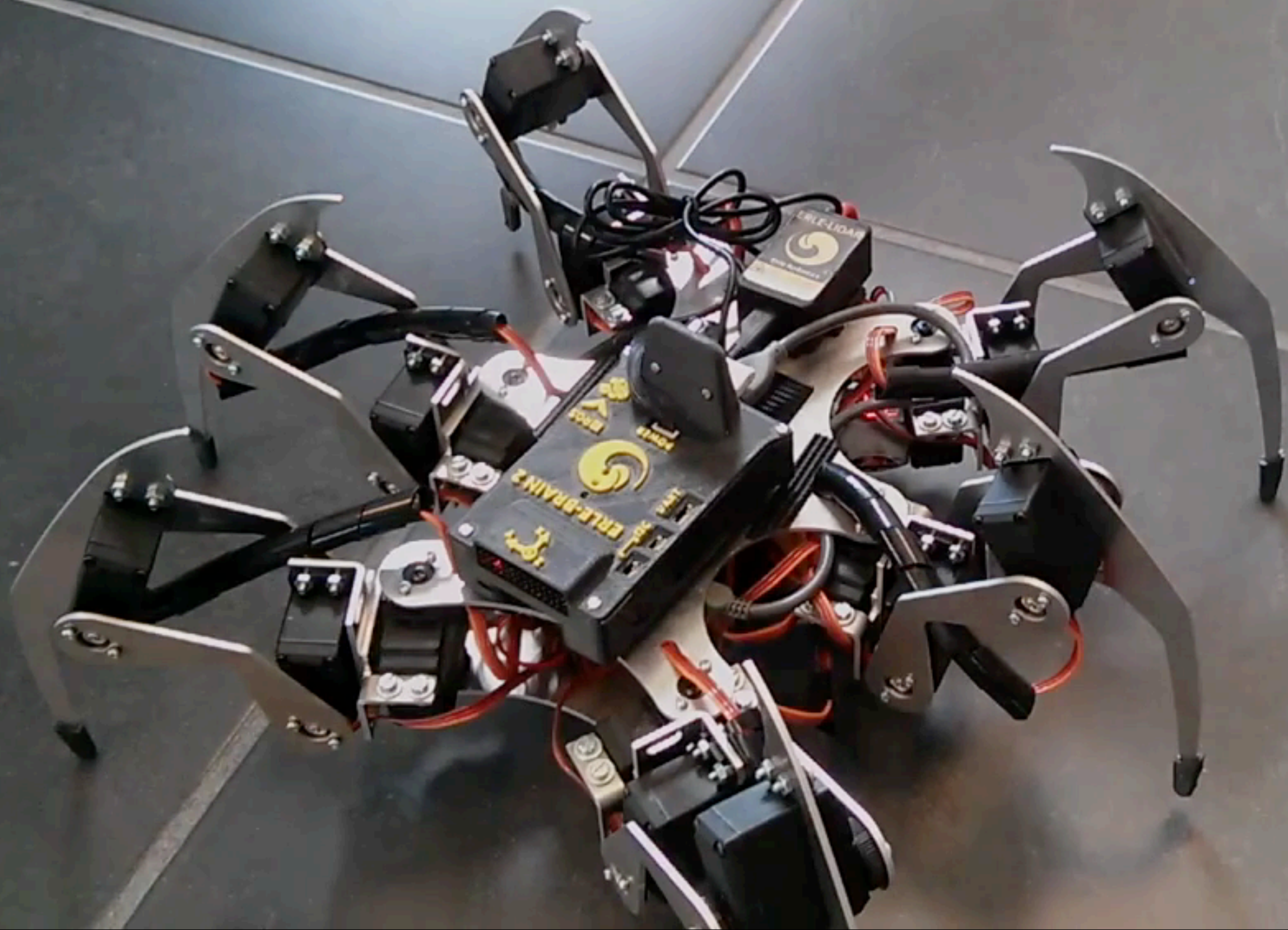


Check if the ROS packages are launched

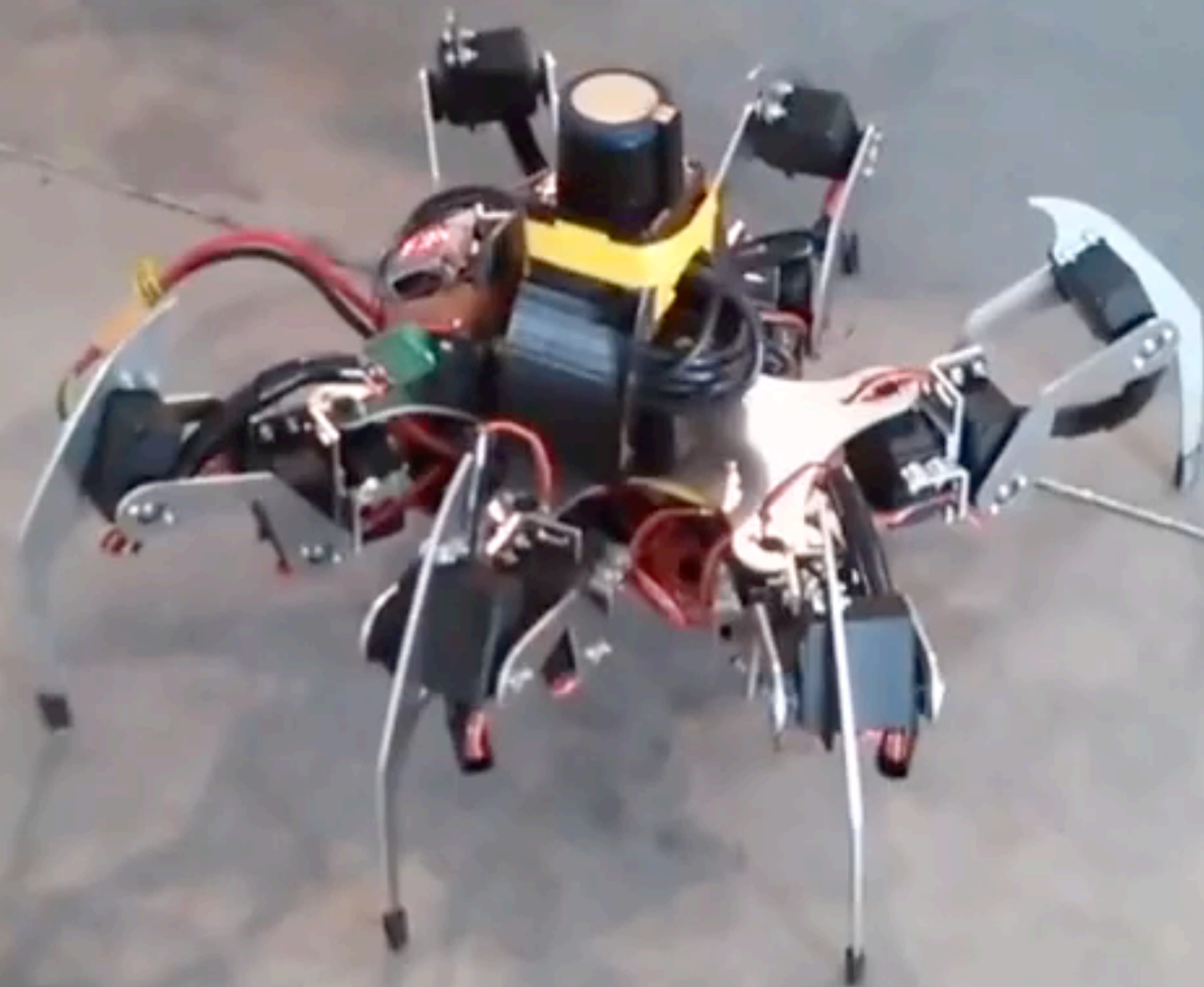
```
1  import rospy
2  import subprocess
3  import rosnode
4  import rospkg
5  from sensor_msgs.msg import Range
6  ros_nodes = rosnode.get_node_names()
7  if not '/lrm30_node' in ros_nodes:
8      rospack = rospkg.RosPack()
9      command = rospack.get_path('lrm30_ros').replace('share', 'lib') + '/lrm30'
10     process = subprocess.Popen(command, shell=True, stdout=subprocess.PIPE)
11     msg_laser = rospy.wait_for_message('/lrm30_data', Range, timeout=1)
```




Demos



```
repeat while true
do
  Camera get color location
  if location == null
  do Wait 2 seconds
  else if location is positive
  do Take a picture
    Turn Right 1 seconds
  else if location is negative
  do Take a picture
    Turn Left 1 seconds
```

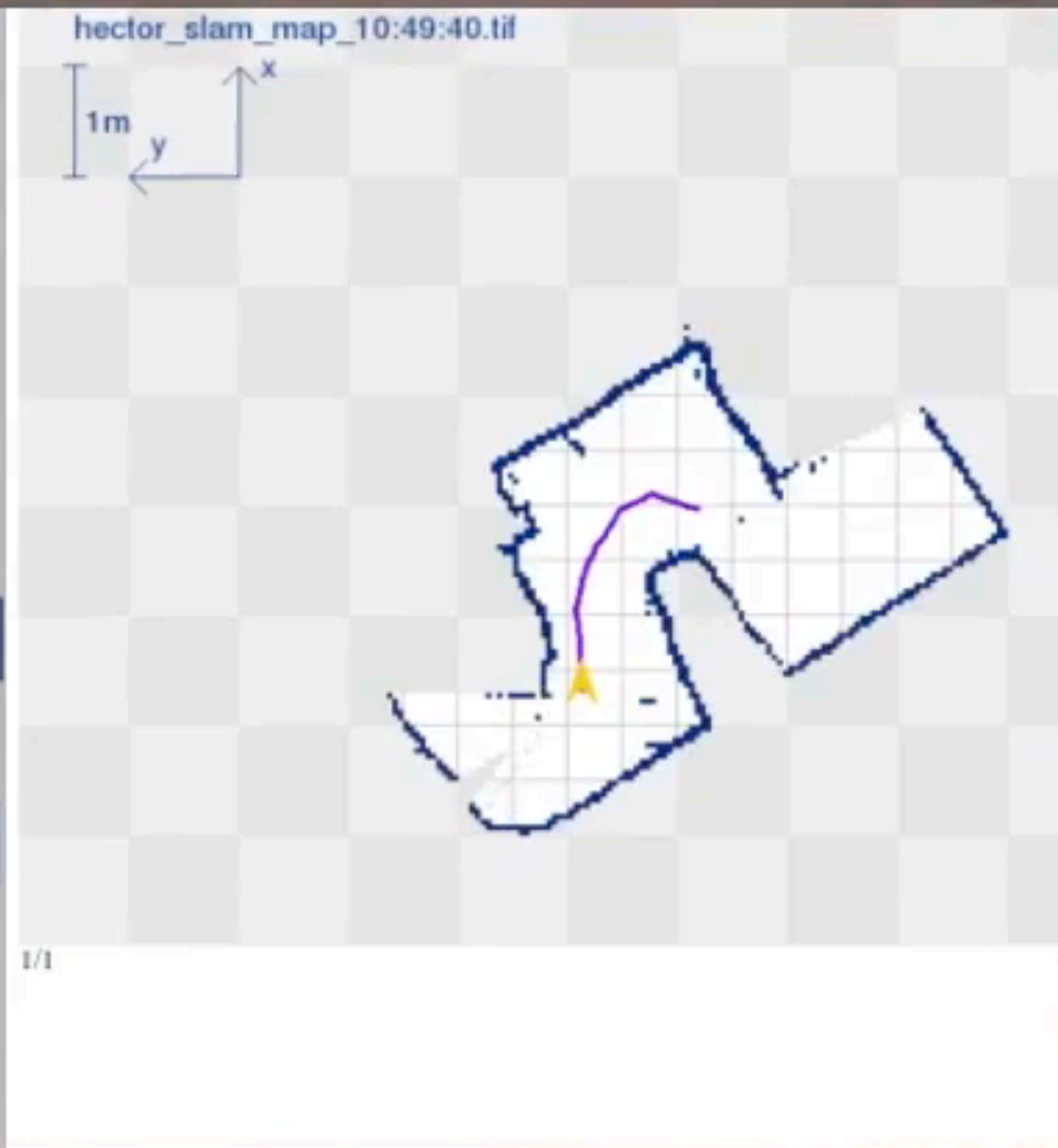



```
Calibrate IMU
Start Hokuyo Laser
repeat while true
do Find path path_angle
  if path_angle < 135
  do
    set R_Deg to 135 - path_angle
    Turn Right R_Deg degrees
  else
    set L_Deg to path_angle - 135
    Turn Left L_Deg degrees
  Walk Forward 5 seconds
```



```
Calibrate IMU
Start Hokuyo Laser
repeat while true
do
  Start slam
  Avoid_Obstacles

to Avoid_Obstacles
  Find path path_angle
  if path_angle < 135
  do
    set R_Deg to 135 - path_angle
    Turn Right R_Deg degrees
  else
    set L_Deg to path_angle - 135
    Turn Left L_Deg degrees
  Walk Forward 5 seconds
```



Conclusions



This kind of package makes easy how to teach robotics



Makes accesible robotics without “programming skills”



Labview or Simulink are not easily extensible



Companies using robot_blockly



Open Source GPLv3

Ready to jump into robotics?



Contact



Erle Robotics S.L.



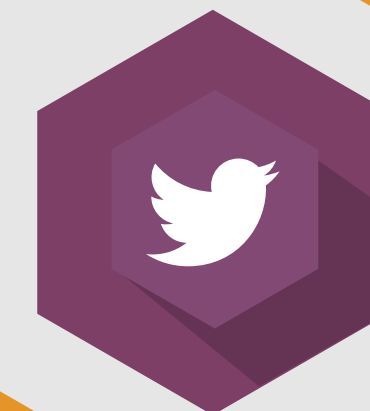
erlerobot



<https://erlerobotics.com>



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