



Introducing the New turtle Jihoon Lee, Yujin Robot



TurtleBot1

Great!













TurtleBot1

Great!



- Open source
- Easy to customize
- Low-cost



TurtleBot1

Problems!



- H/W limitation
- No Active Maintainer
- No Github
- Distribution







What are the improvements?



Yujin Robot's iClebo Kobuki



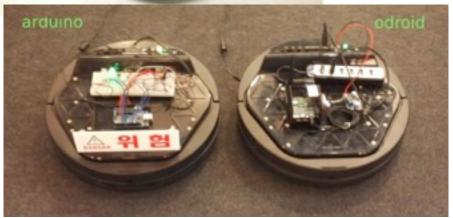
- 1. Long operation time (3/7 hrs)
- 2. Precise odometry (built-in gyro)
- Flexibility(Multiple Power-source)



Yujin Robot's iClebo Kobuki





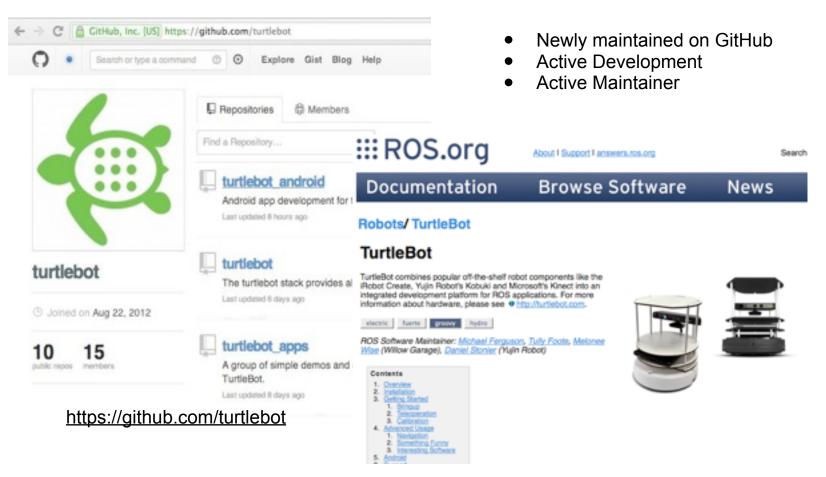






Copyright@2013 YUJINROBOT All reserved

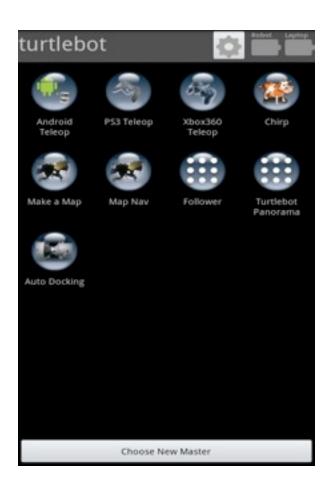
Software



http://www.ros.org/wiki/Robots/TurtleBot



Software - Android



- All apps are rebuilt with up-to-date version of rosjava
- All apps are available in google play
- Search for OSRF and Yujinrobot for up-to-date version of apps



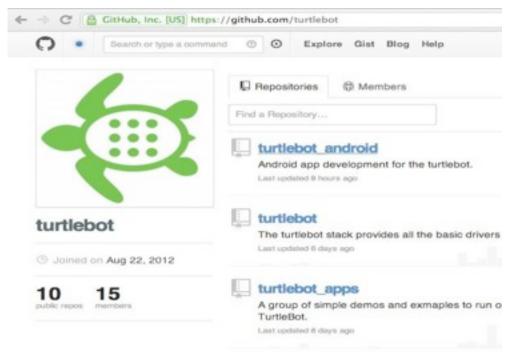
Software - TurtleBot ISO



- Expected Soon!
- Thanks to Bill for huge amount work of handling all complexity of ISO creation



Community



New Players!!





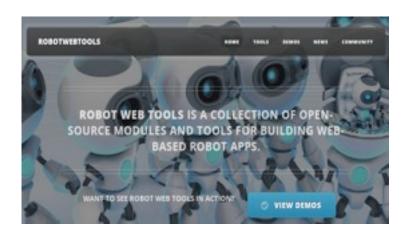
- Encourage community contributions
- Integrate contributions into the official base
- Do the dirty and boring, but necessary jobs

Looking for another new players!

ros-sig-turtlebot@googlegroups.com

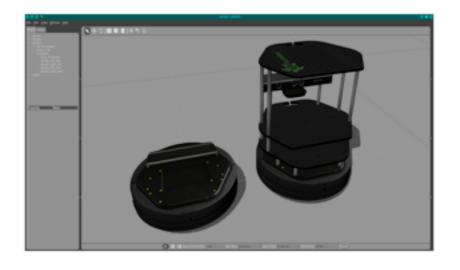


In Future - Expected in Hydro





- New Android app framework
- TurtleBot Web
- TurtleBot Simulation
- Multi-Robot framework





More Information



- ROS wiki : http://www.ros.org/wiki/Robots/TurtleBot
- Github: https://github.com/turtlebot
- TurtleBot SIG : ros-sig-turtlebot@googlegroups.com
- TurtleBot website: http://www.turtlebot.com
- iClebo Kobuki: http://kobuki.yujinrobot.com



QnA

